

## A-2240-04: R-Series 4 Degree-of-Freedom Arm

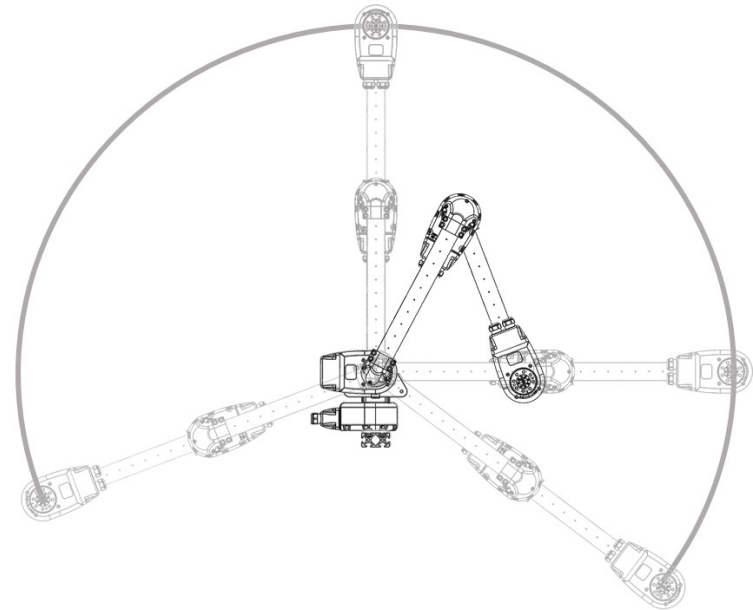
A fully integrated, collaborative, and rugged manipulation platform.



R-Series Actuators *Default Configuration*	HEBI Mounting Brackets and Connection Toolbox Included 1x R8-3 (Wrist) 3x R8-16 (Base, Shoulder, and Elbow)
Mechanical Features	IP67 (Dust-Tight and Temporary Submersion) T-Slot Extrusion Mounting (80/20®) Easy integration of additional components or sensors
Software	Joystick Control with the HEBI Mobile I/O App (iOS & Android) Example code in MATLAB, ROS, Python, and C

Weight (w/ Gripper Assembly)	4.0 kg
Max Reach	650 mm
Payload* @ Max Reach	1.0 Kg
Half Reach	325 mm
Payload* @ Half Reach	3.0 kg
Gripper Max Finger Torque (R8-9)	1.1 Nm
Gripper Max Finger Force (50mm from Pivot)	23 N
Parallel Gripper Stroke Length	82 mm
*Payload calculated using default arm configuration <b>without</b> a gas spring* Arm configuration is customizable upon request.	

### Workspace



Request a quote at [www.hebirobotics.com](http://www.hebirobotics.com)