



R-Series 5-DoF Arm Kit

Assembly Instructions

General Warnings and Cautions

Danger (May cause serious injury or death)

- Keep water, flammables, solvents and other liquids clear from **unsealed** actuator.
- Keep fingers away from moving parts during operation.
- Cut power immediately if actuator emits strange odors or smoke.
- Keep actuator out of reach of children.

Warning (May cause injury or damage to actuator)

- Do not expose the actuator to permanent and strong magnetic fields.
- Do not force screws into the bottom of the actuator. R8 = 8mm Tap Depth
- Use provided hardware with accessories and hand tighten as needed.
- Attempts to disassemble actuator will void the warranty and may cause permanent damage.

Sealing (R-Series Actuators are IP67 when properly used)

- Please refer to all online documentation for proper sealing techniques of the actuator.

For more information please visit: ***docs.hebi.us***

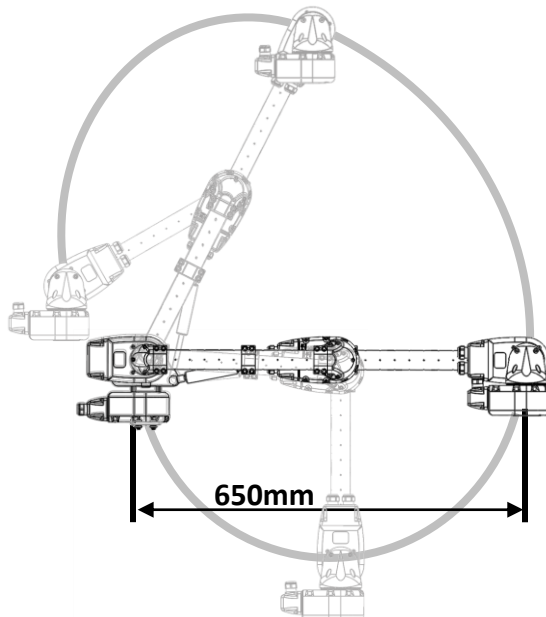
Technical Specifications

Specifications	Value
Weight	6.00 kg
Reach	700 mm
Payload at Max Reach*	1.00 kg
Payload at Half Reach*	5.00 kg

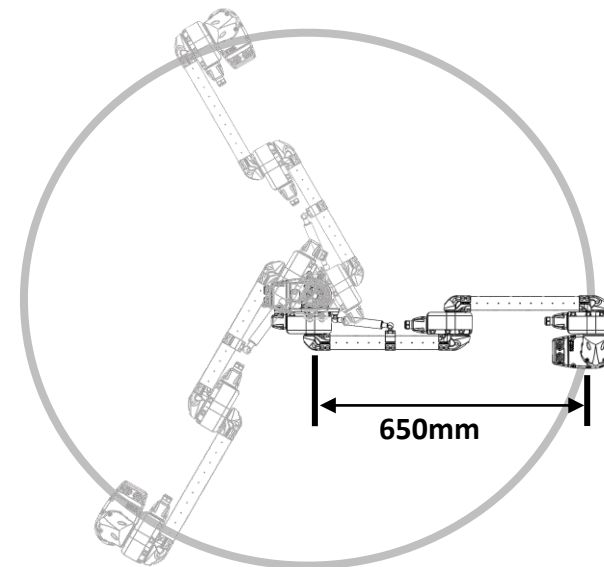
Calculated using Default Configuration with Gas Spring.
Using a different configuration of R-Series Actuators will provide different payload capacities.

Movement	Working Range	Speed
Axis 1 – Base [Default: R8-16]	Continuous (limited by wiring)	90°/s
Axis 2 – Shoulder [Default: R8-16]	0° to +70° (limited by gas spring)	90°/s
Axis 3 – Elbow [Default: R8-16]	-155° to +155° (avoid end effector collisions)	90°/s
Axis 4 – Wrist 1 [Default: R8-3]	Continuous (avoid end effector collisions)	504°/s
Axis 5 – Wrist 2 [Default: R8-3]	Continuous (limited by wiring)	504°/s

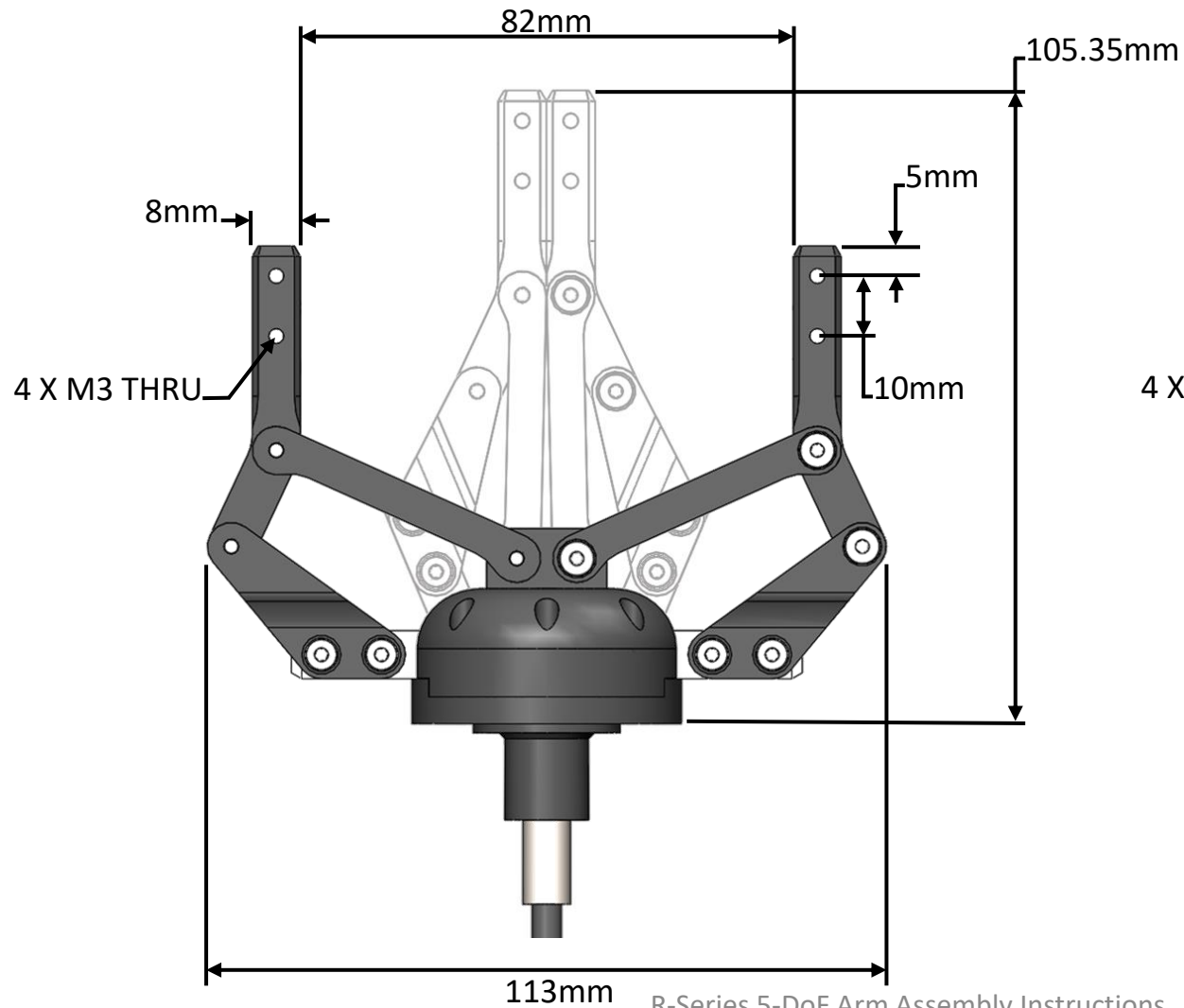
Side View



Top View



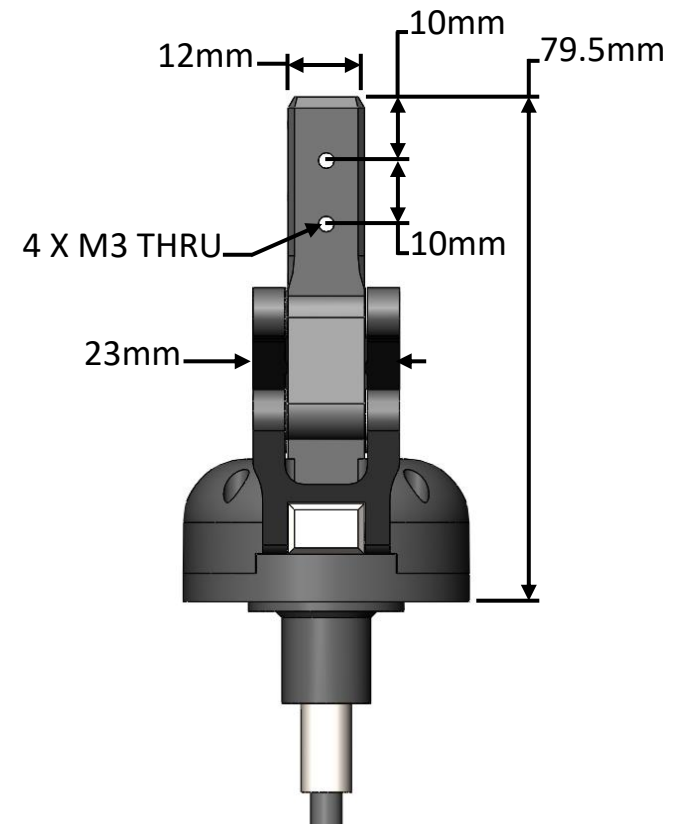
Technical Specifications



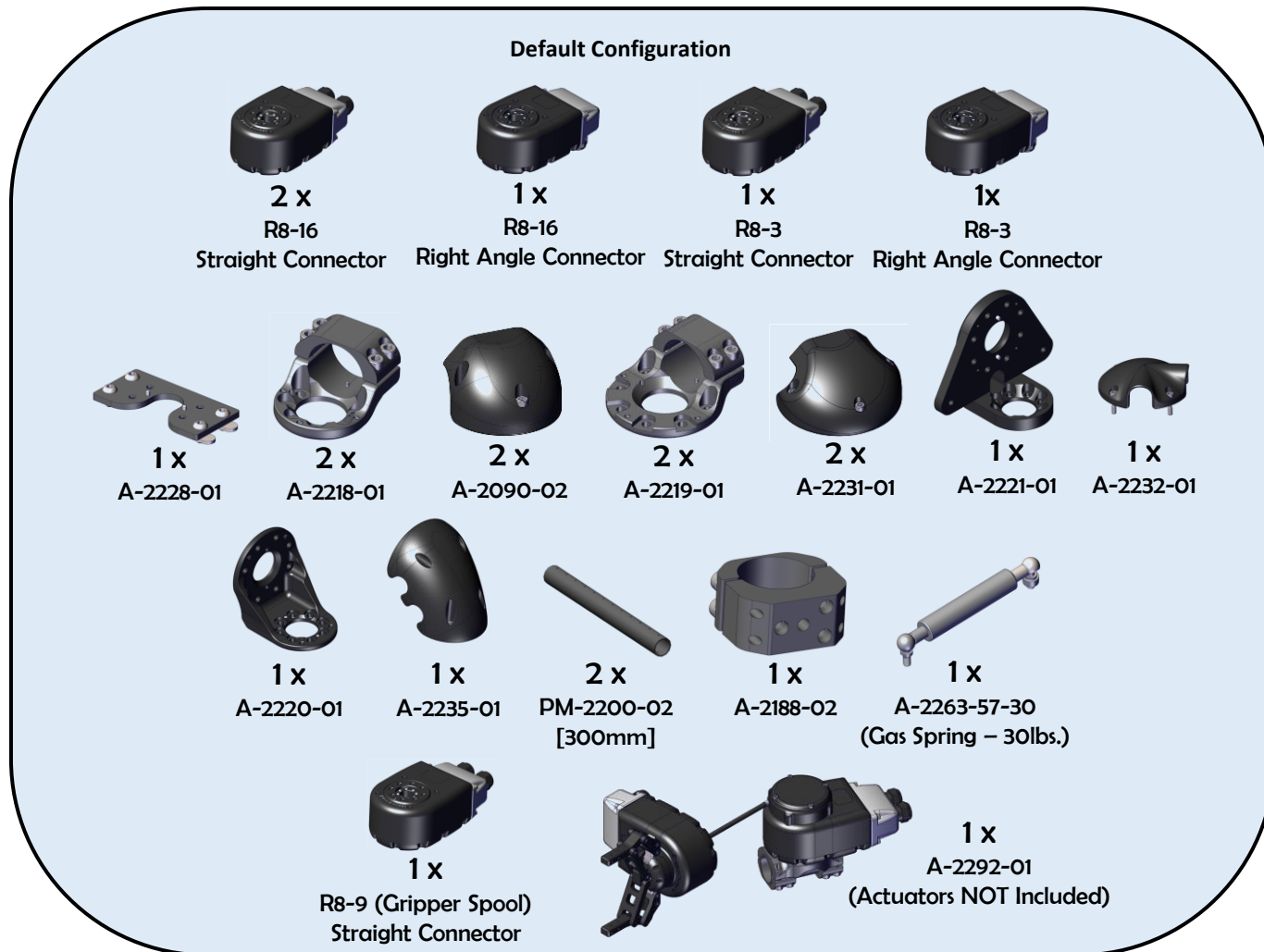
Spool Module	Max Finger Torque	Max Finger Force at 50mm
R8-3	0.4 Nm	8 N
R8-9**	1.1 Nm	23 N
R8-16	2.0 Nm	40 N

* Values assume a symmetric two-finger grasp

** Default Module



Bill of Materials – Mechanical*



fasteners included, not shown

Bill of Materials - Electrical



PP-2349-RED
18AWG Power Wire, Red



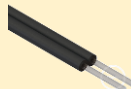
PP-2349-BLK
18AWG Power Wire, Black



PP-2358-YEL
22AWG M-Stop Cable, Yellow



PP-2358-BLU
22AWG M-Stop Cable, Blue



PP-2401-DUP
POF Duplex Cable

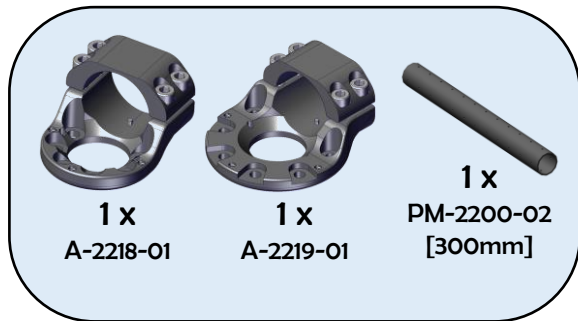
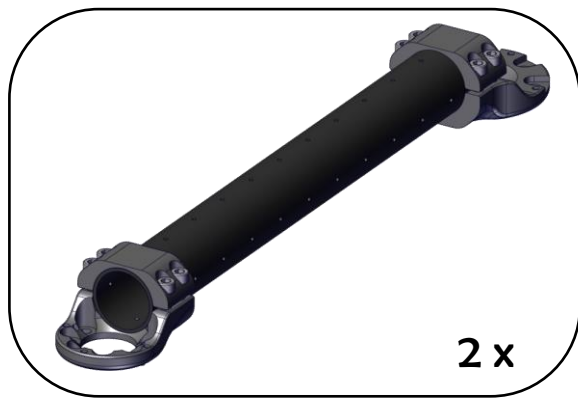


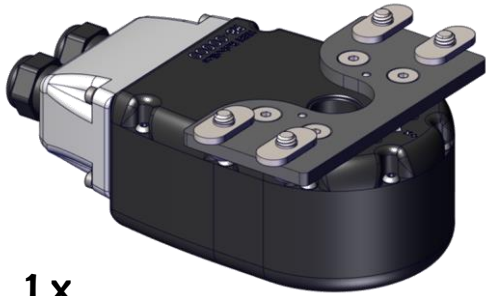
A-2256-01
POF Ethernet Media Converter

all items are included in R-Series Connection Toolbox

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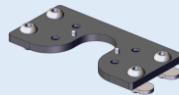
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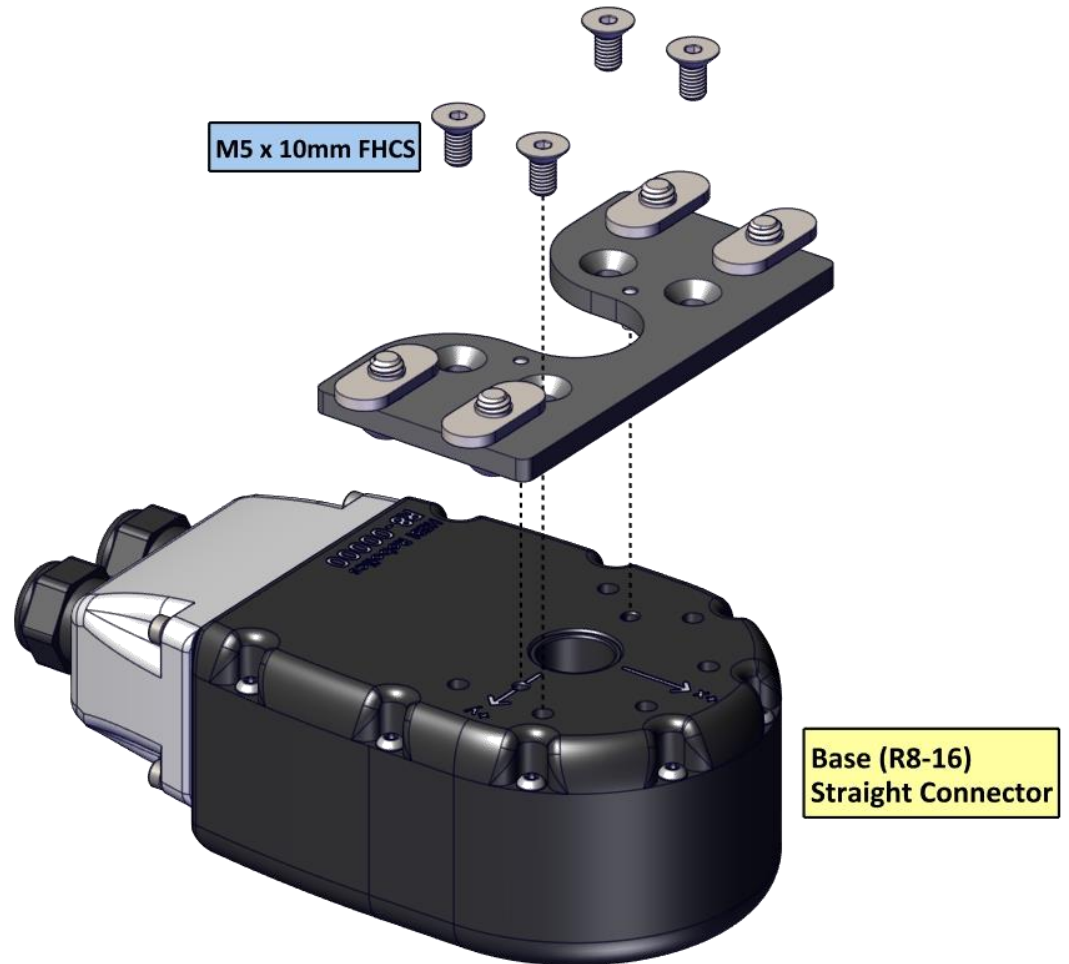
R8-16

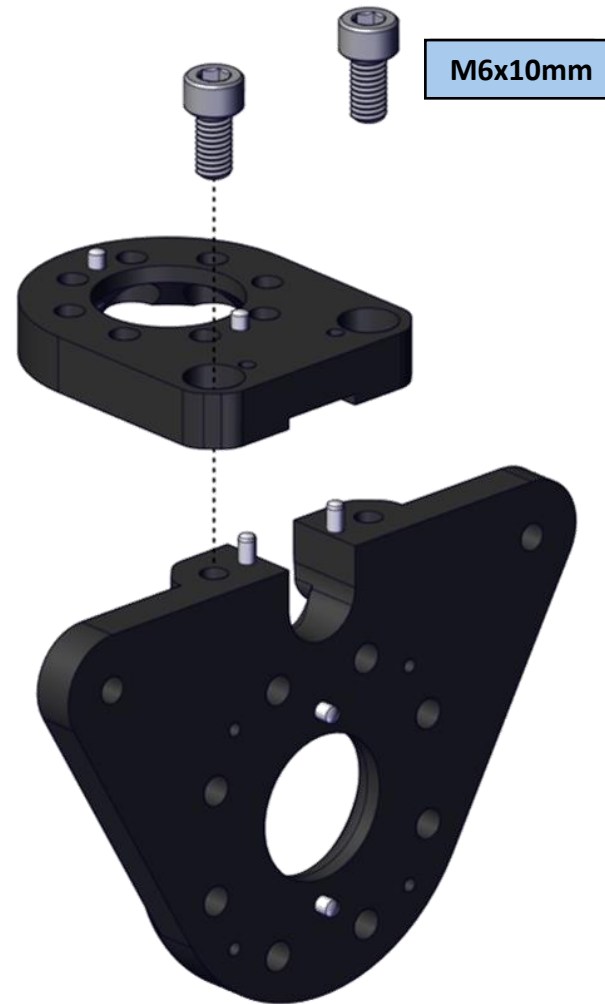
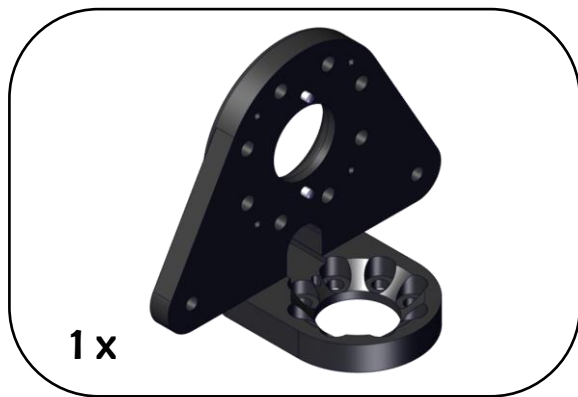
Straight Connector



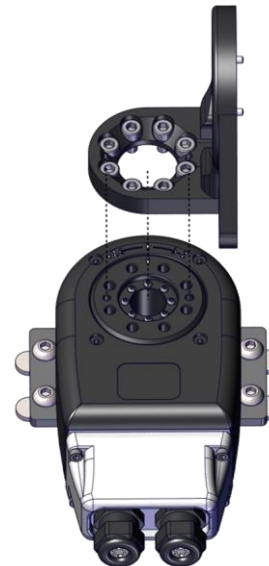
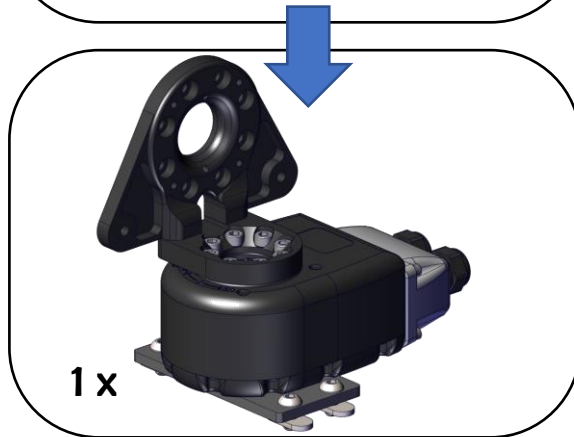
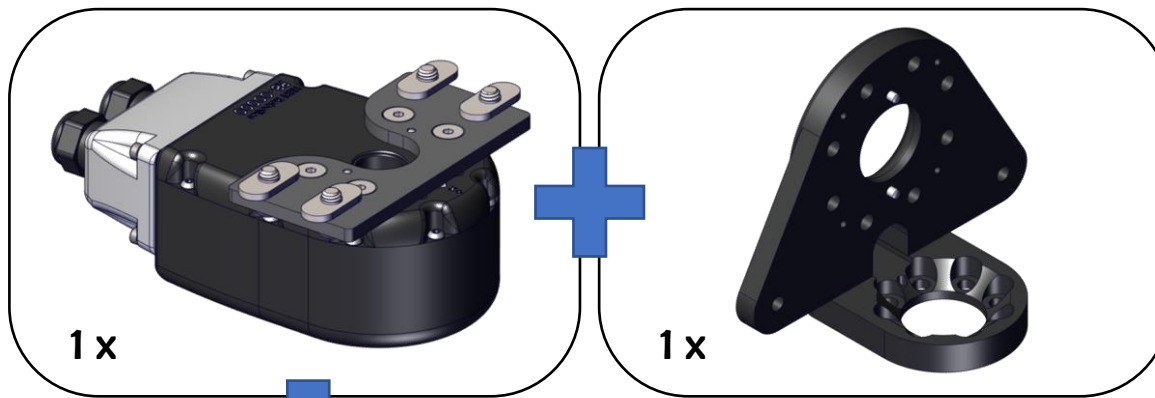
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A-2228-01



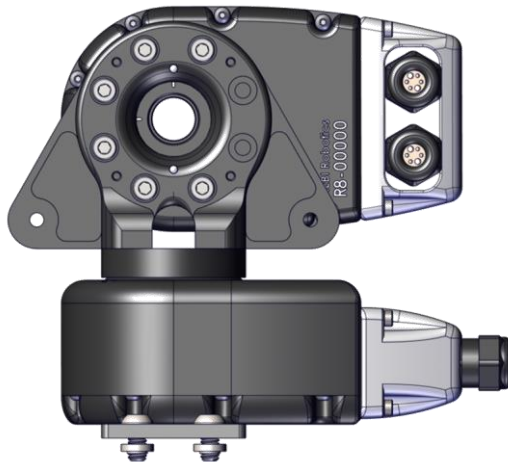
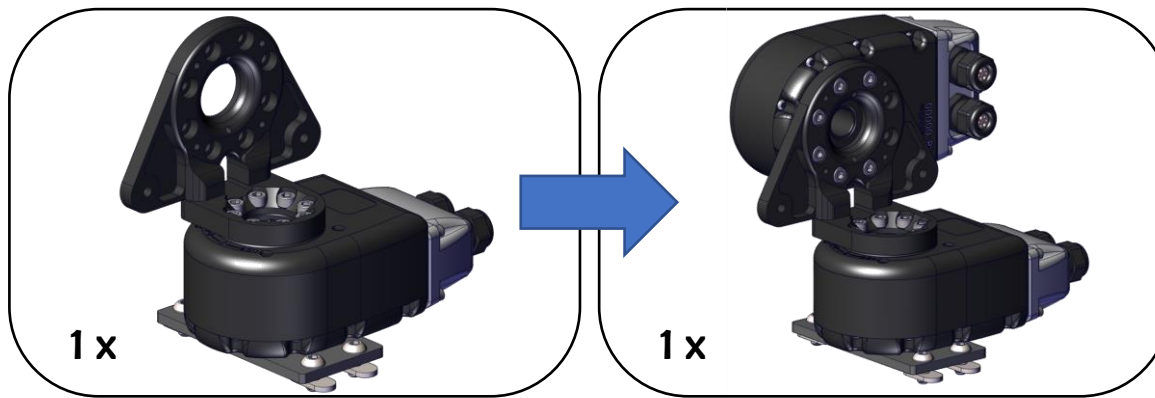


Flat face towards outside

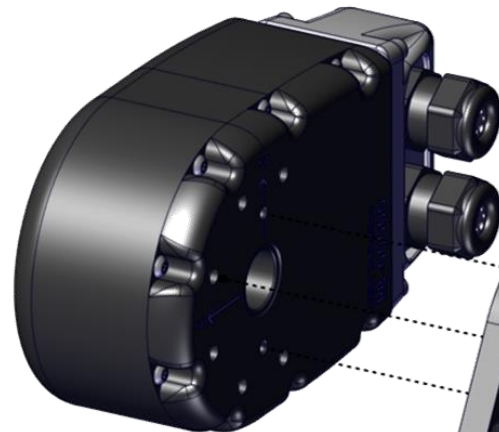


 **Align with actuator
output hub tick mark
(Flat face parallel with tick mark)**

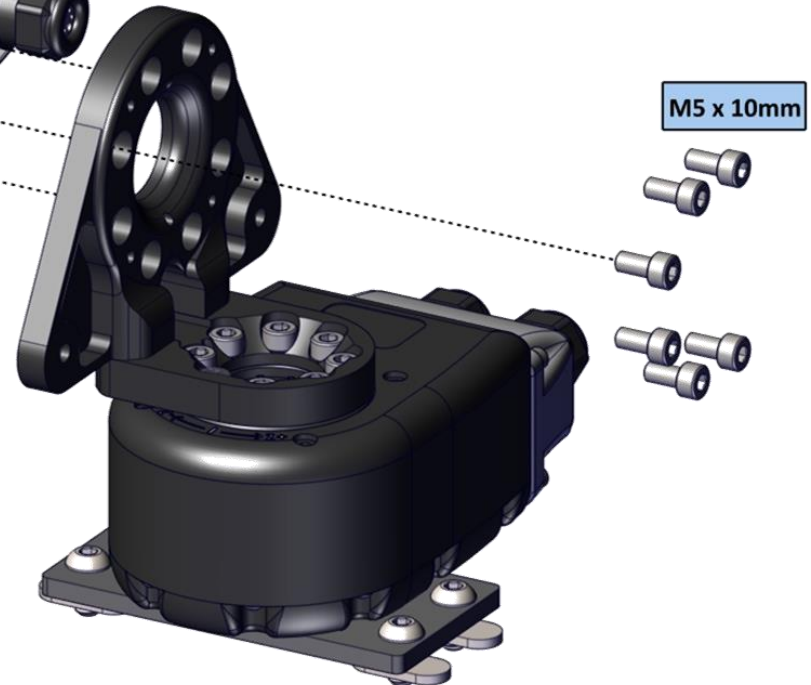


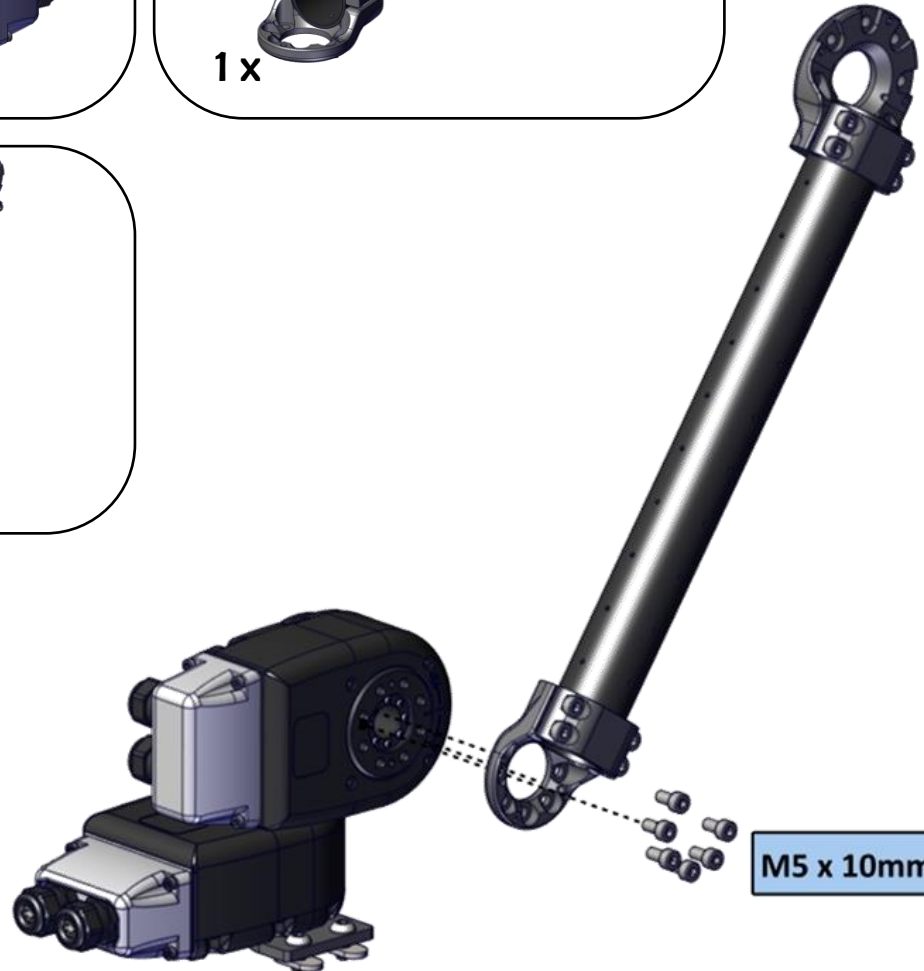
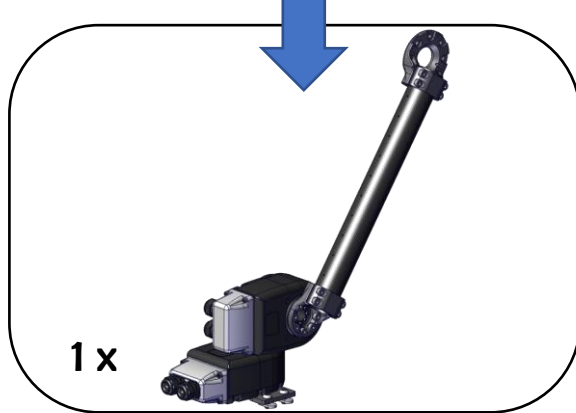
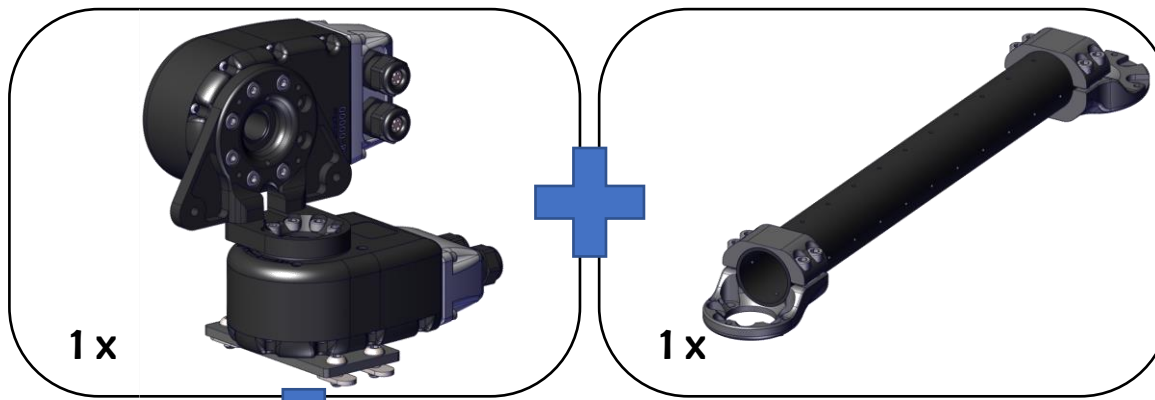


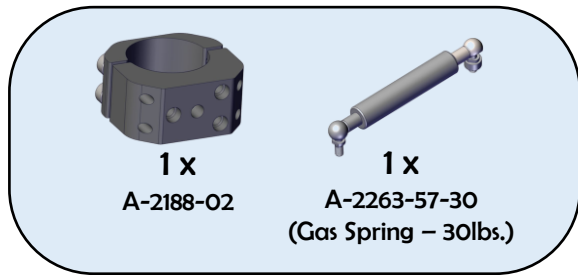
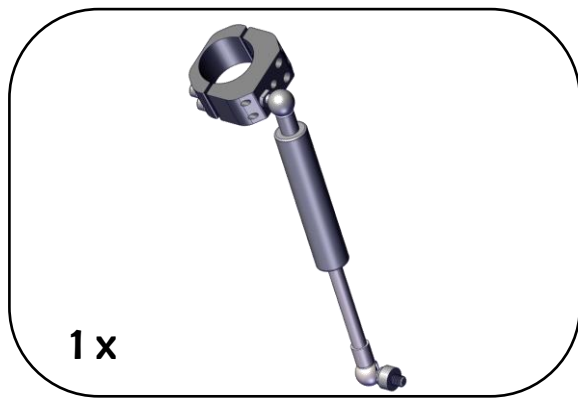
Connectors of both modules
point the same way

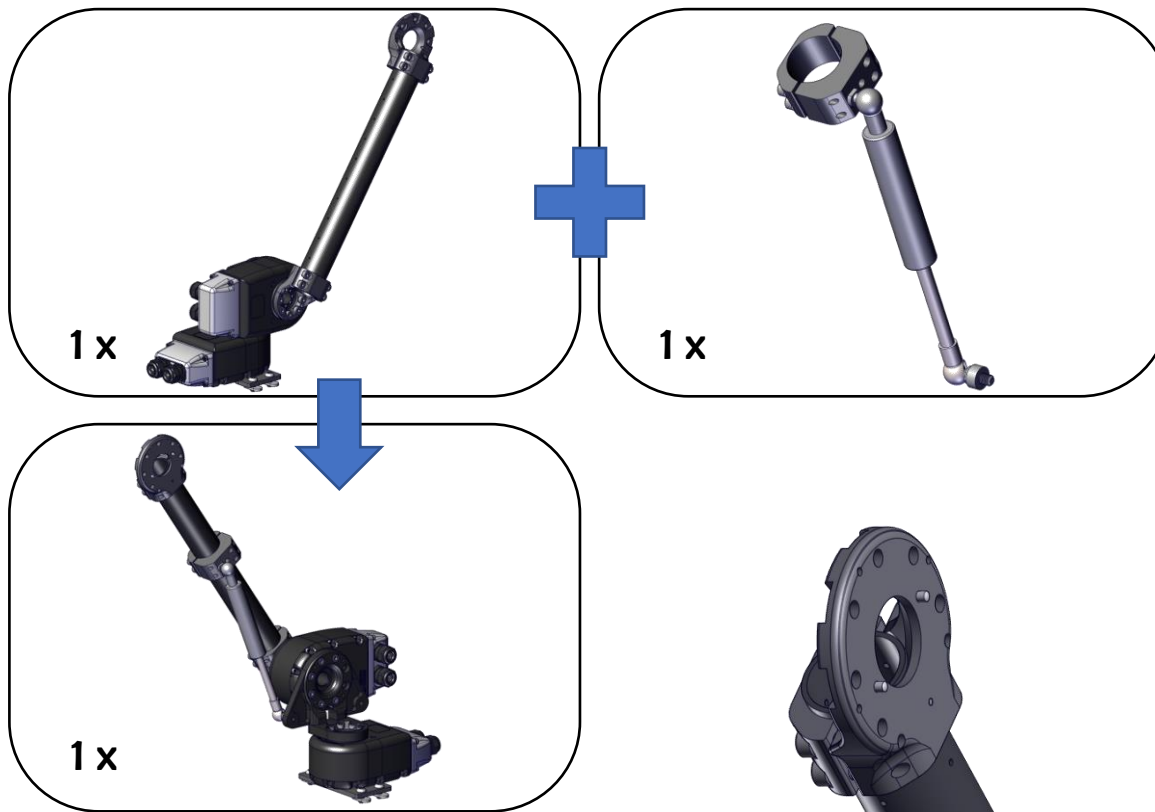


Shoulder (R8-16)
Right Angle Connector









1 x

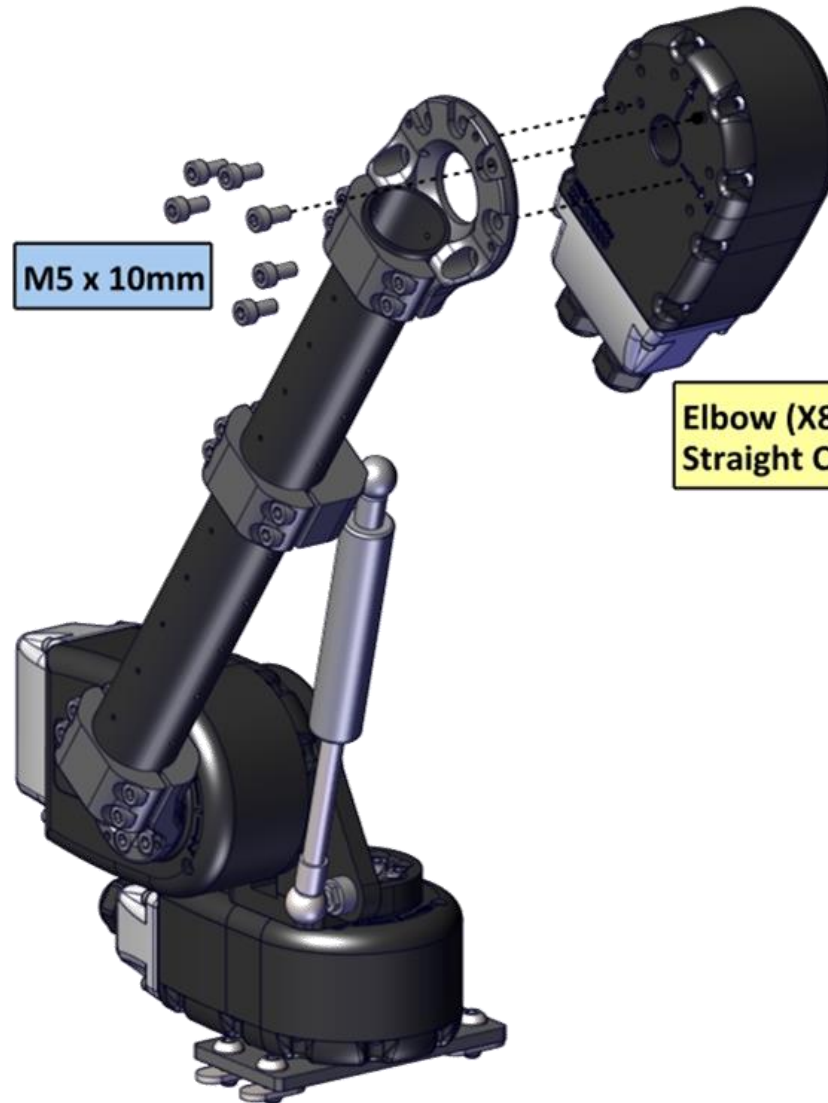


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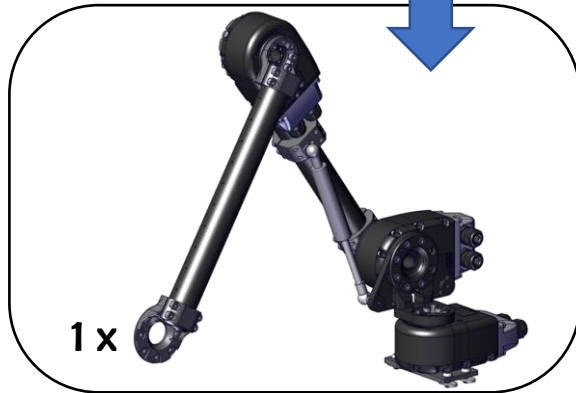
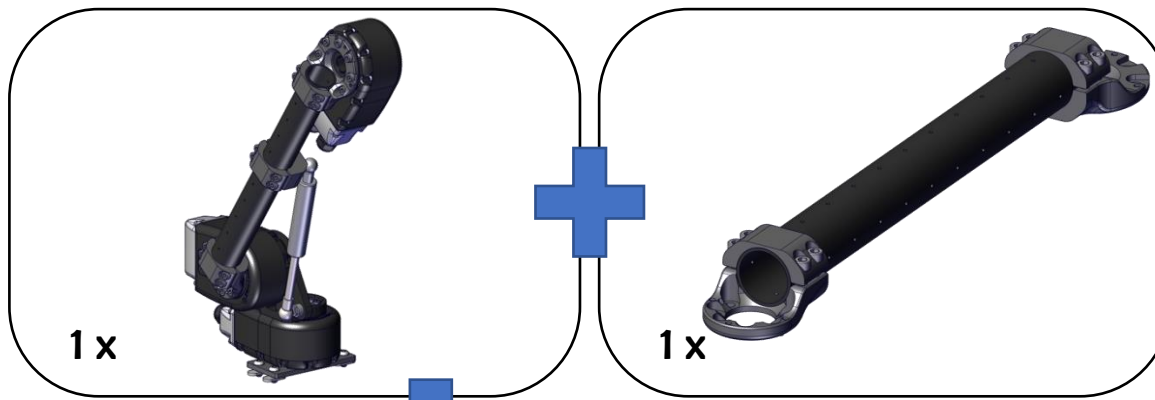
R8-16


Straight Connector

M5 x 10mm



Elbow (X8-16)
Straight Connector



 Align with actuator
output hub tick mark
(Tube aligns with tick mark)



1 x



1 x

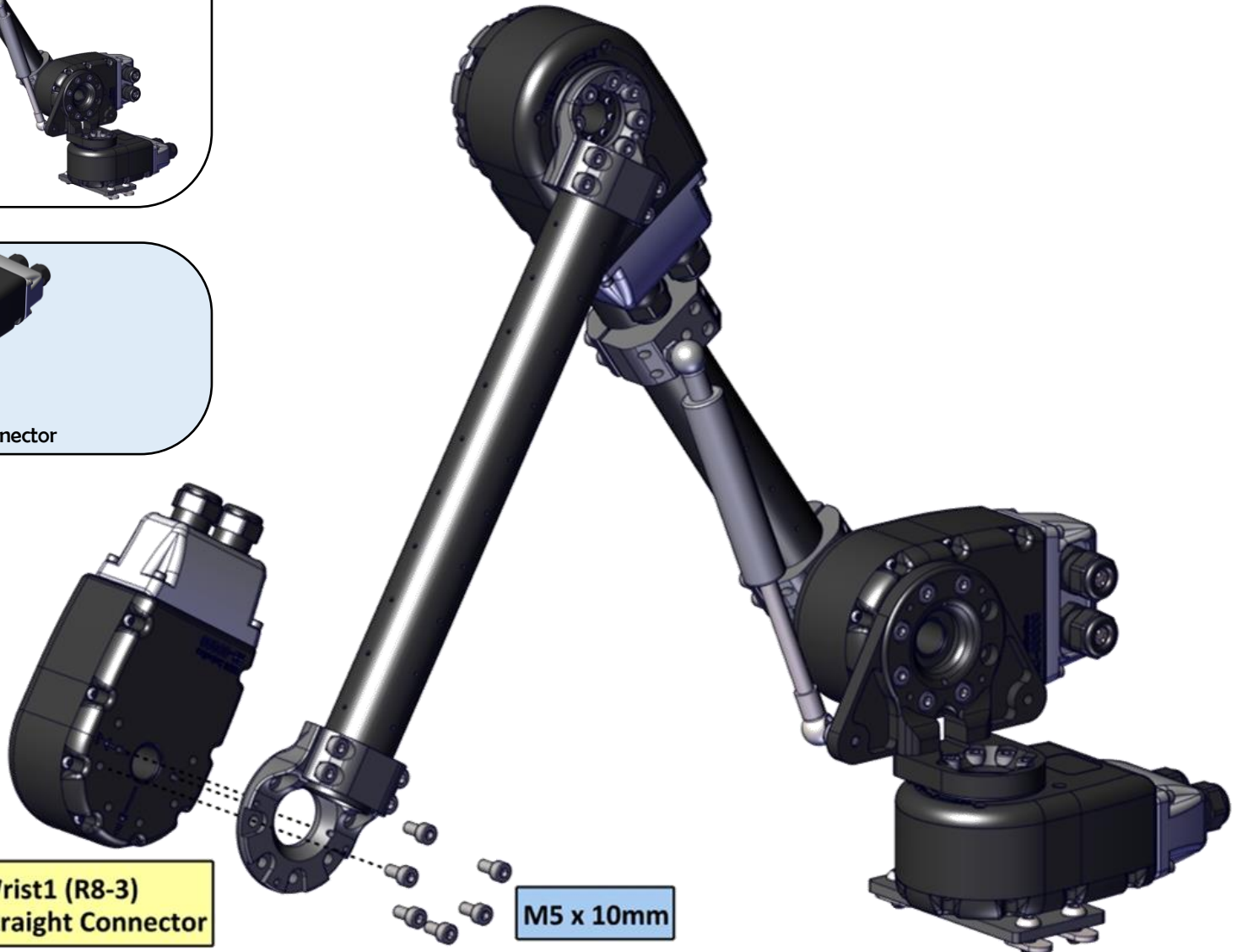
R8-3

Straight Connector



Wrist1 (R8-3)
Straight Connector

M5 x 10mm

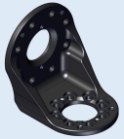


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A-2220-01

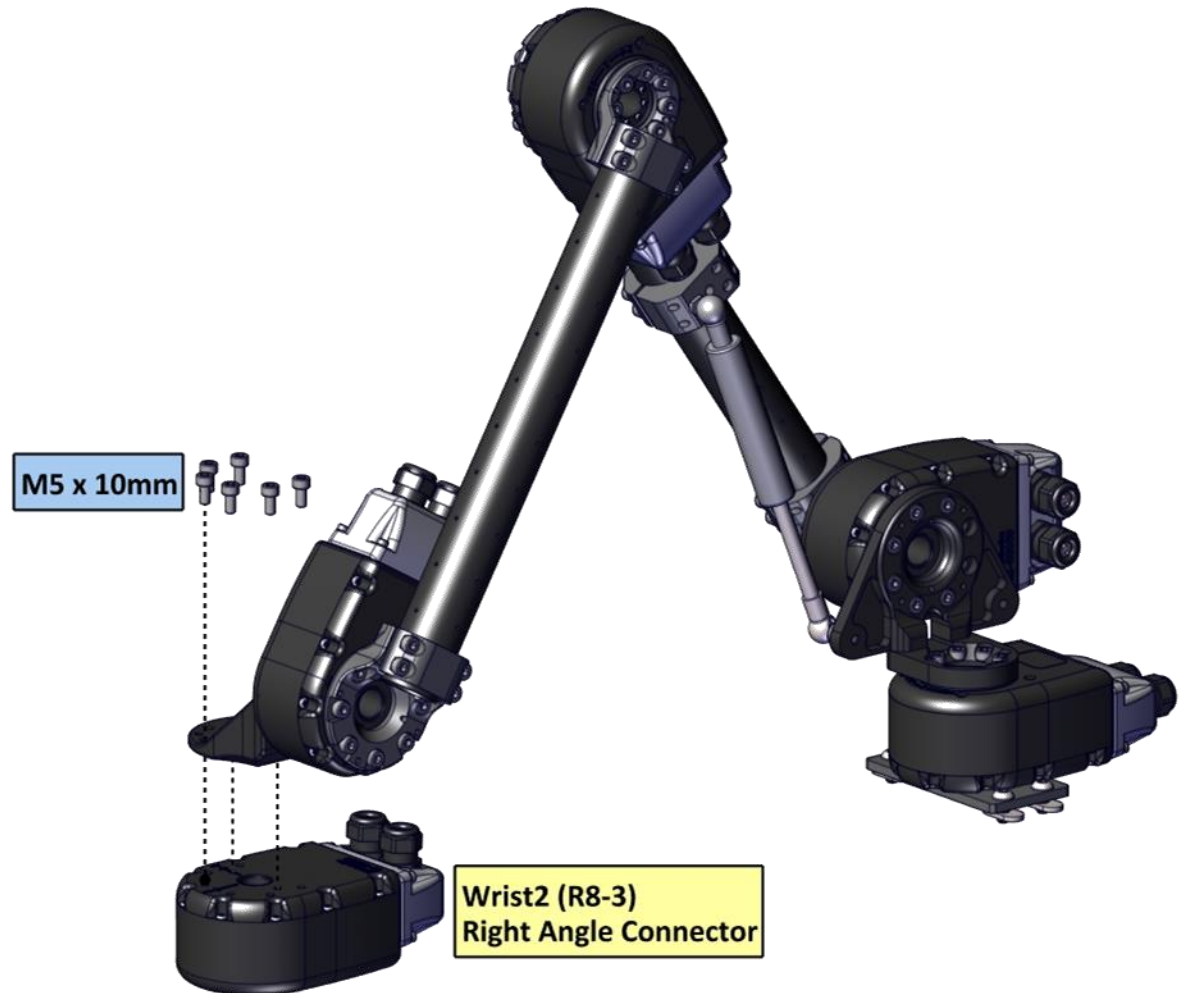
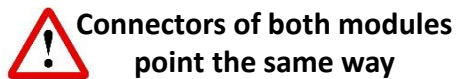
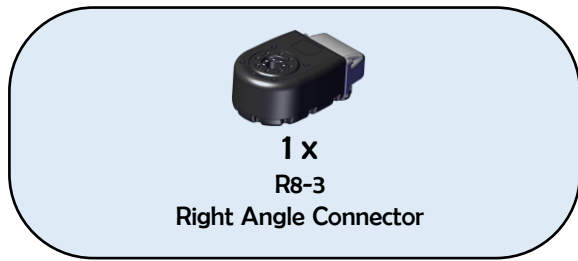


Align with actuator
output hub tick mark
(Flat face parallel with tick mark)



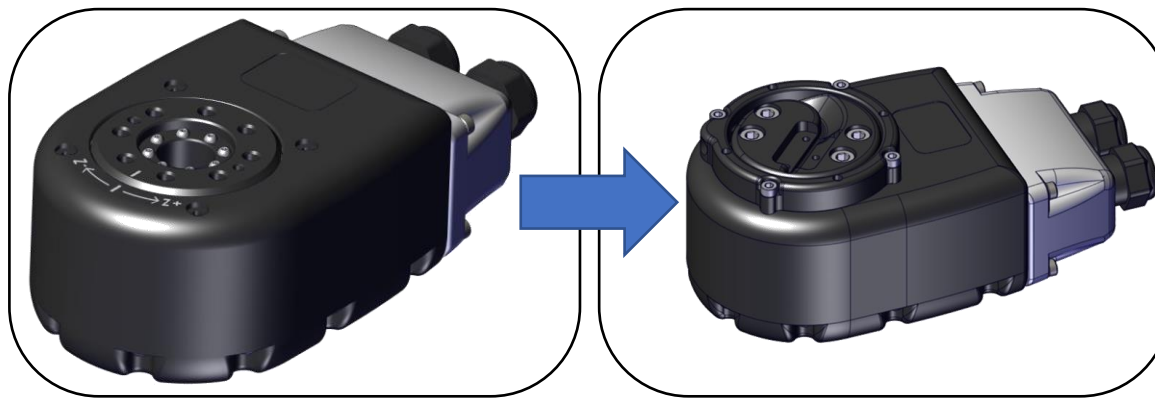
M5 x 10mm

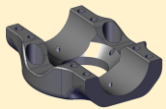
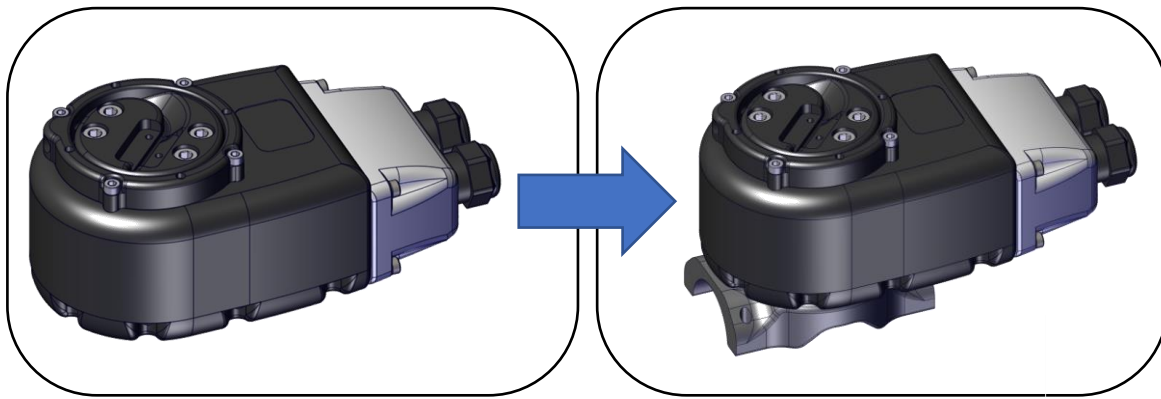




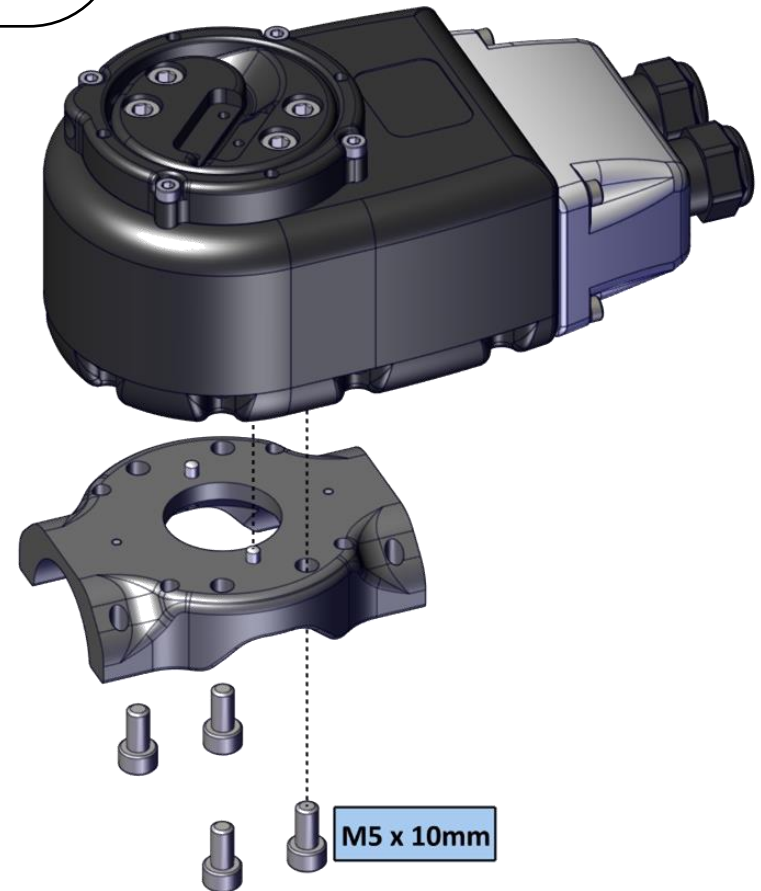


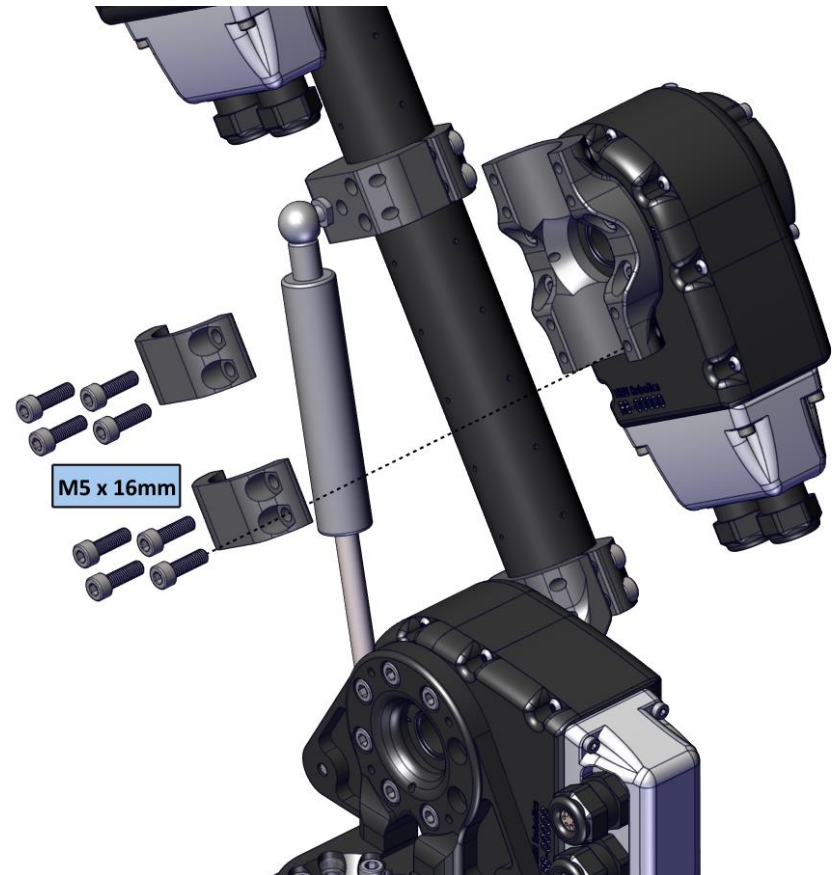
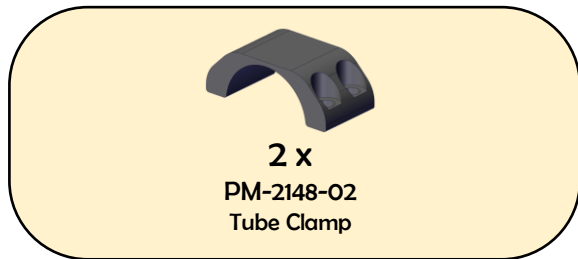
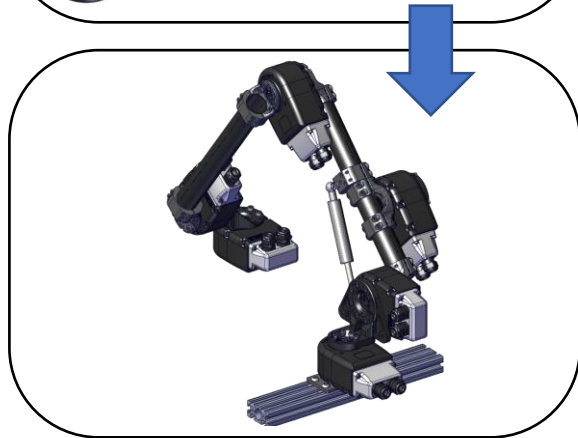
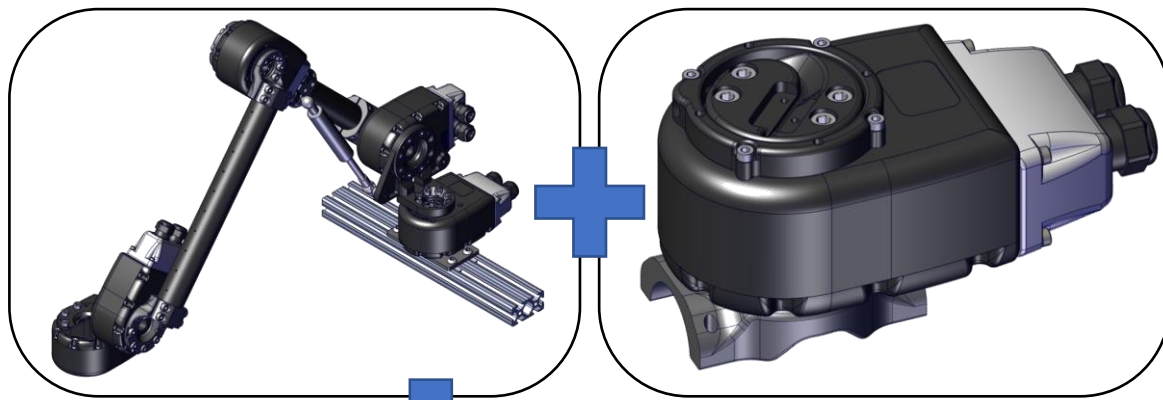
Gripper

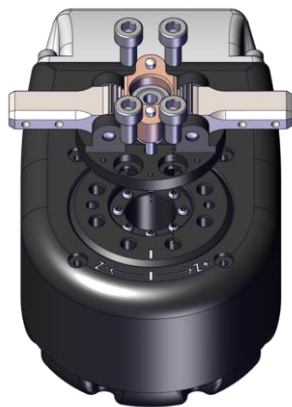
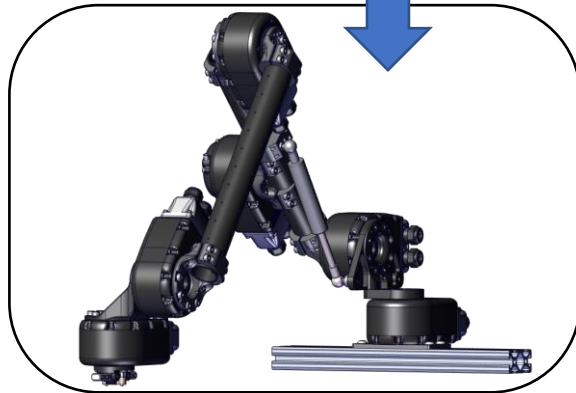
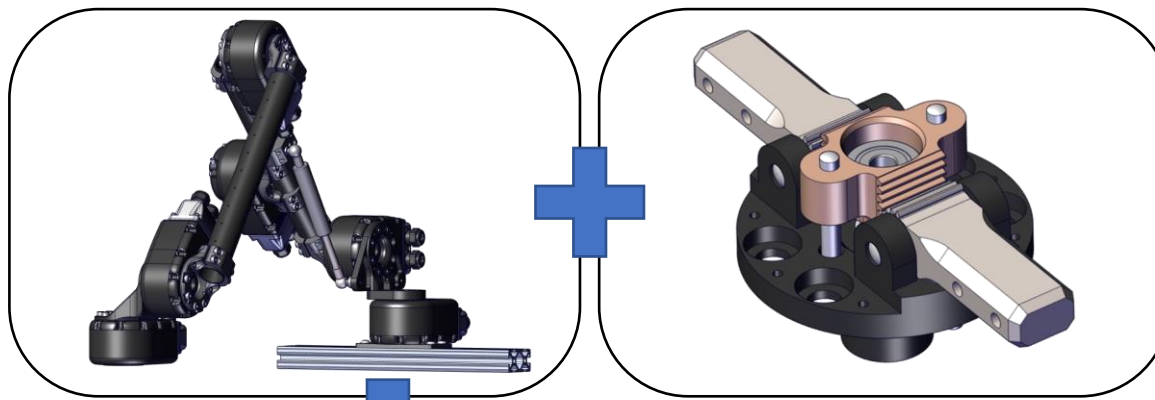




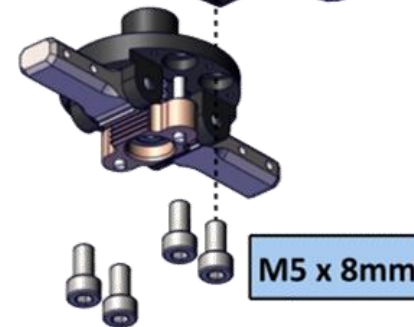
1 x
PM-2519-01
Housing Mid-Tube Mount







 **Align with actuator
output hub tick mark**
(Fingers perpendicular to the tick mark)



Wiring Notes

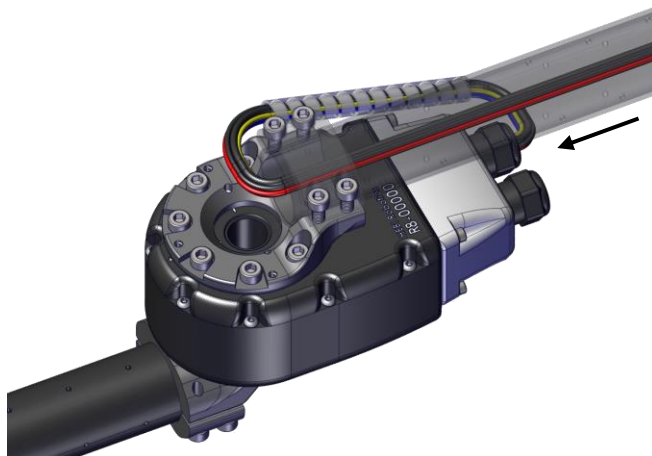
- Keeping wires organized will help prevent tangling and add a nice aesthetic.
 - Spiral sleeving is a good accessory for organizing loose wires
- Visit the following link to see detailed instruction on connecting wires to R-Series Modules.

<http://docs.hebi.us/#r-series-quickstart>

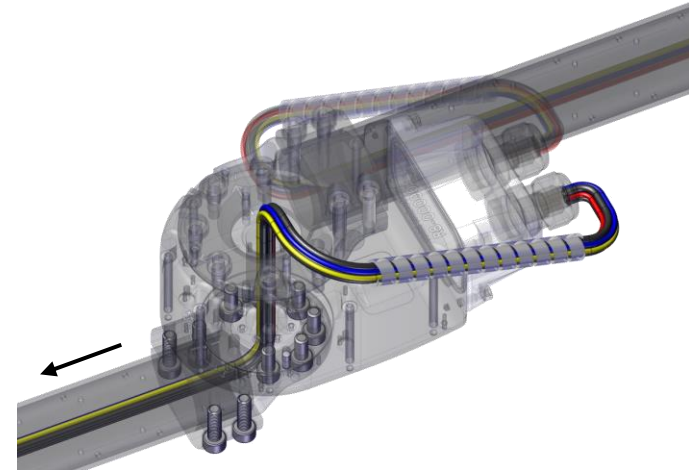
For more information visit: ***docs.hebi.us***



[Spiral sleeving]

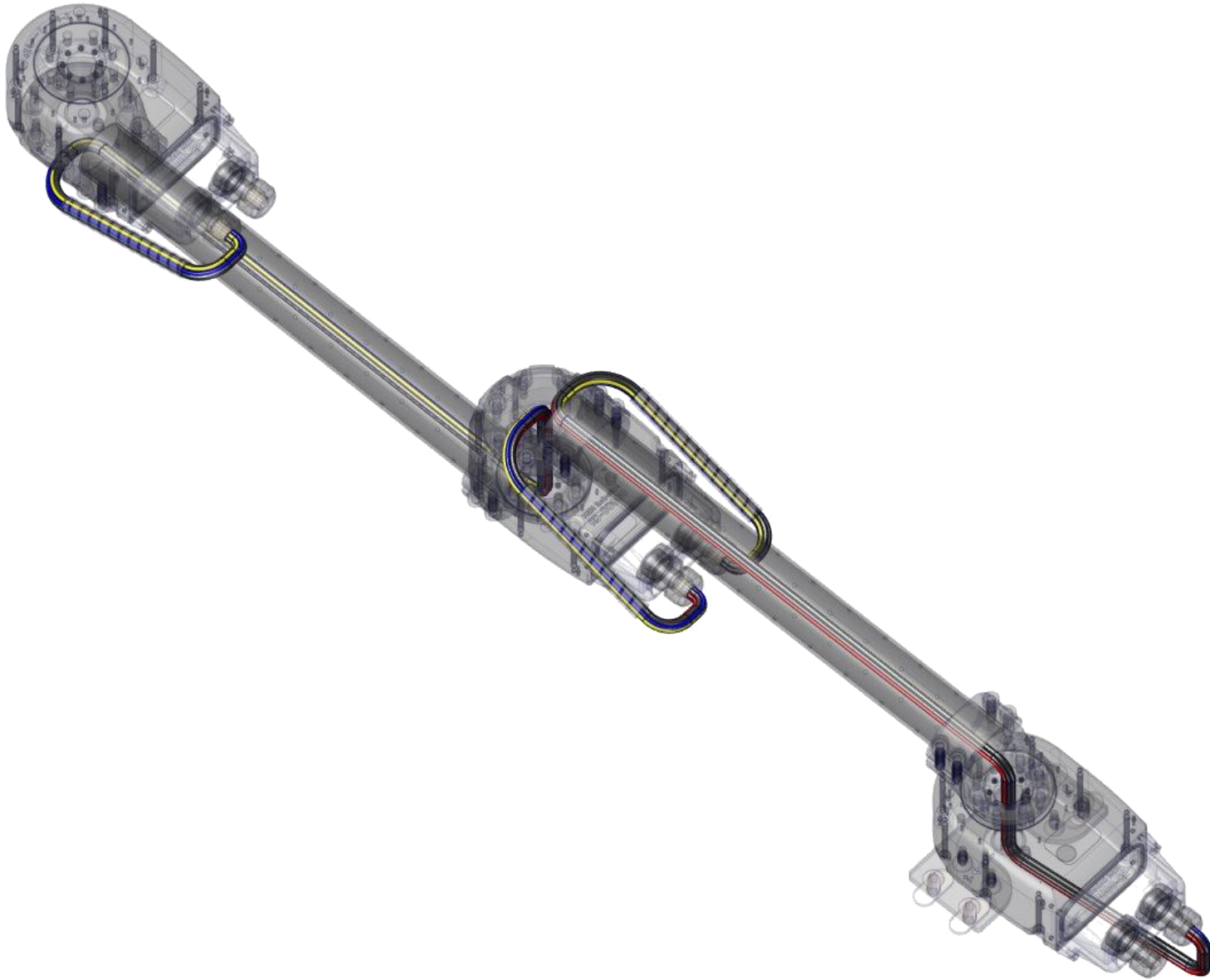


Wires that come from the previous joint should be inserted directly to actuator ports.

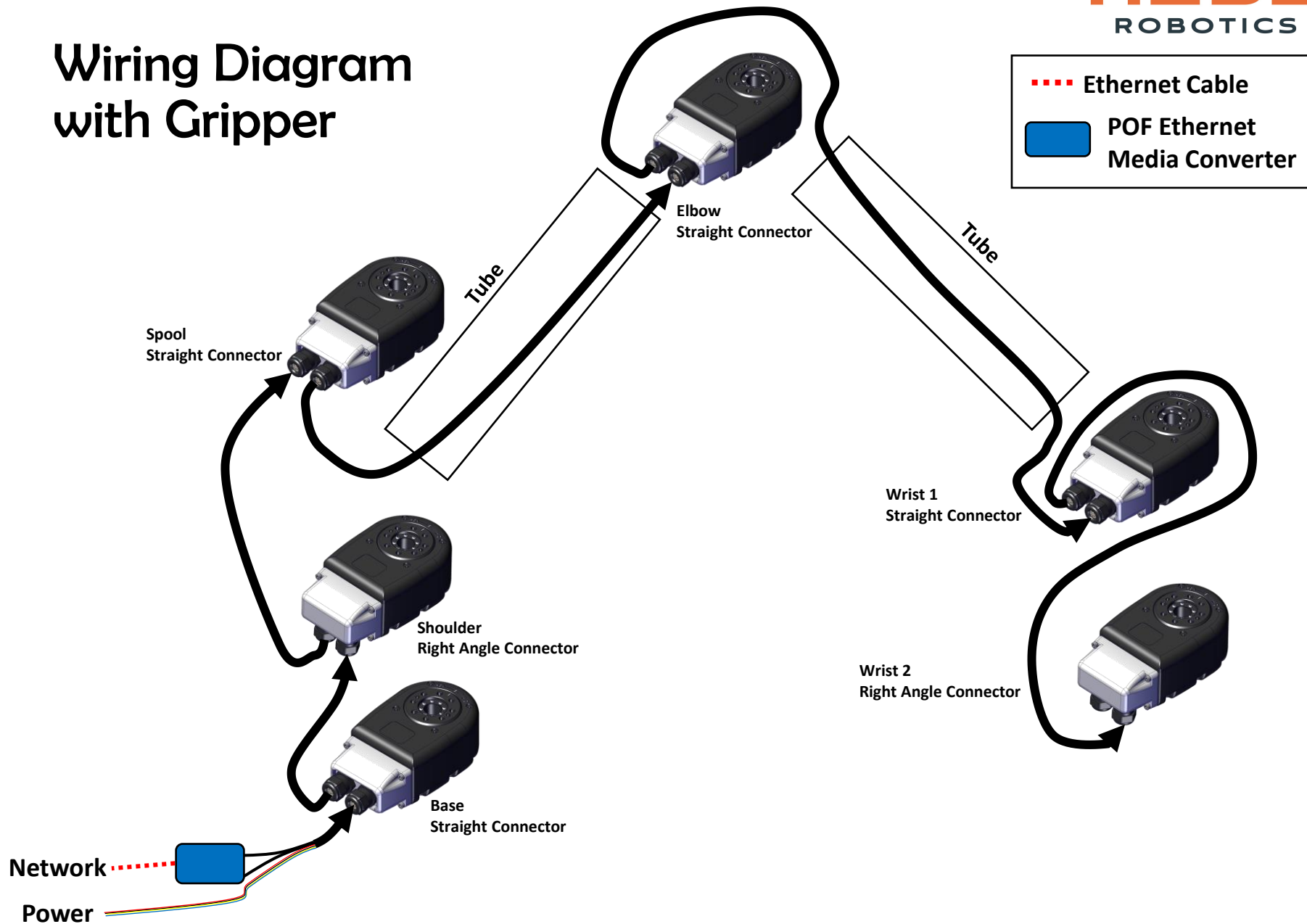


Wires that connect to the next joint should be threaded through the actuator's bore hole.

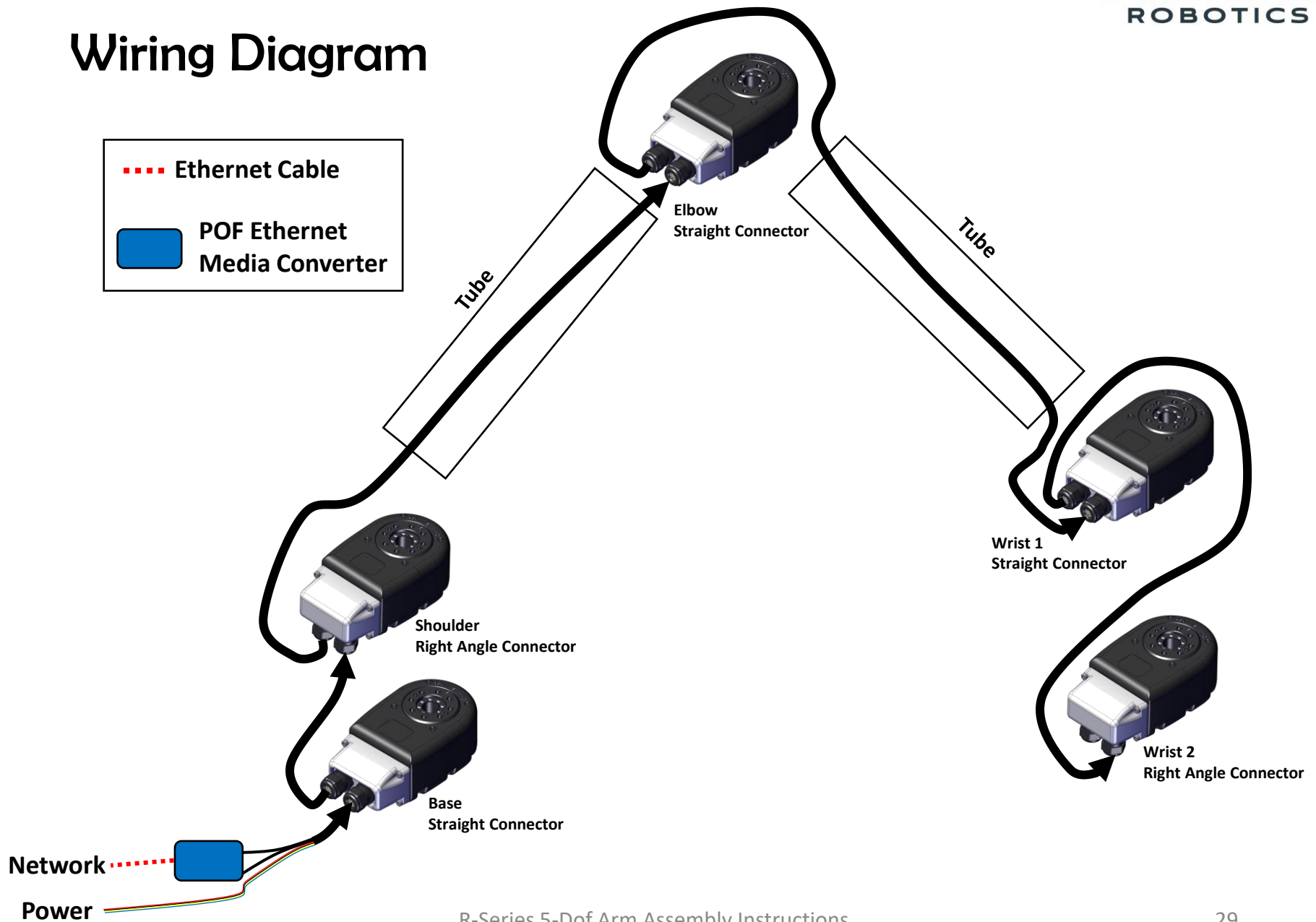
Wiring Example



Wiring Diagram with Gripper

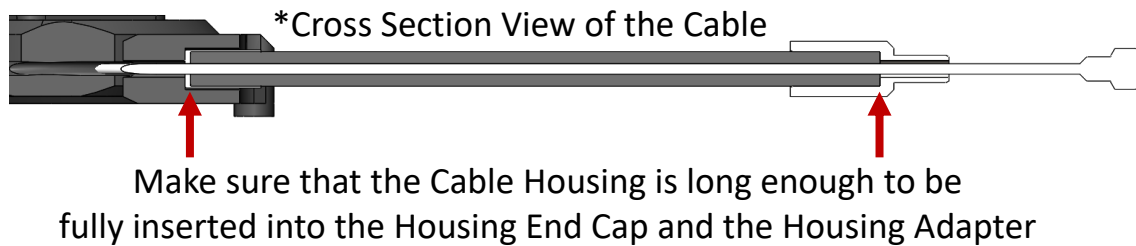


Wiring Diagram



Running the Cable Through

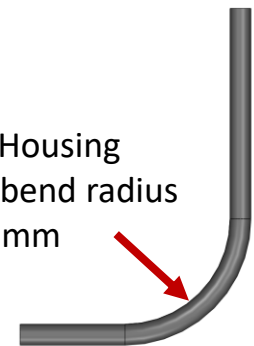
- Make sure to use a Standard Road Bike Brake Cable.
- Run the cable to fit your system.
- Run both the cable and the cable housing before cutting them to ensure that the cable is long enough.
- Cut the cable housing first, and then cut the cable.

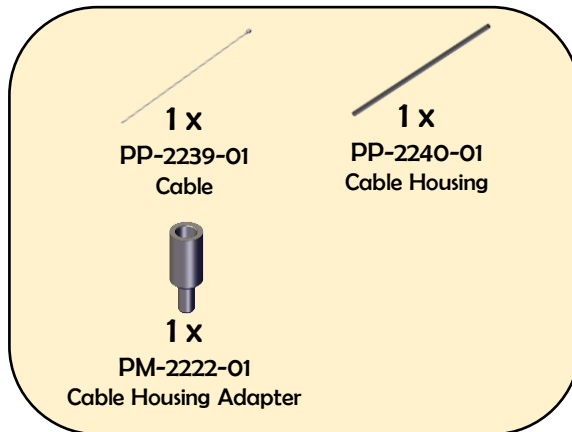
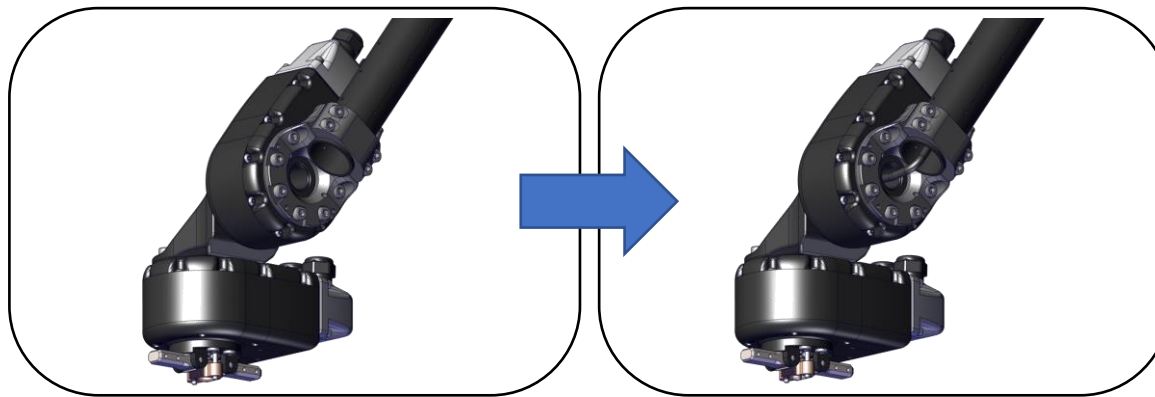


About 100mm of Cable should stick out from the Cable Housing

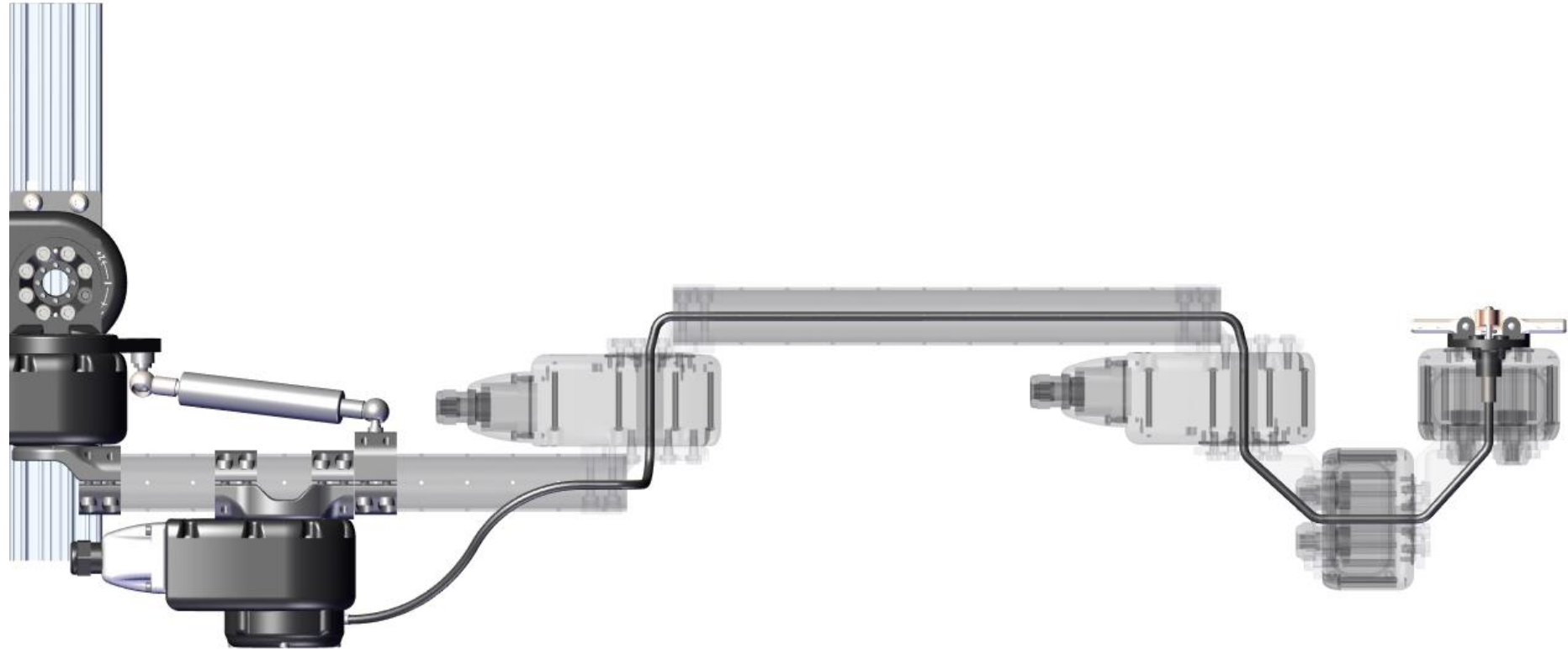


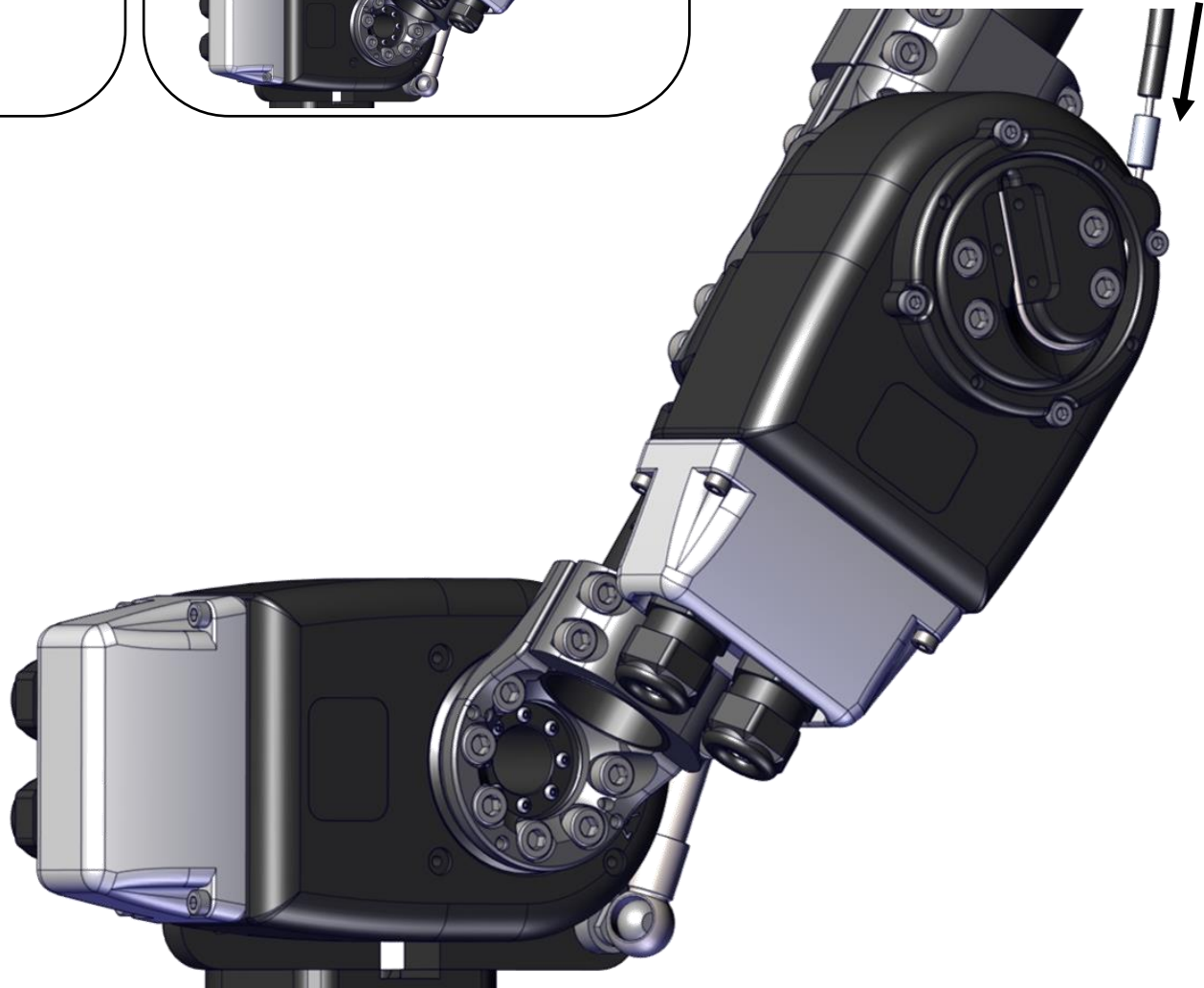
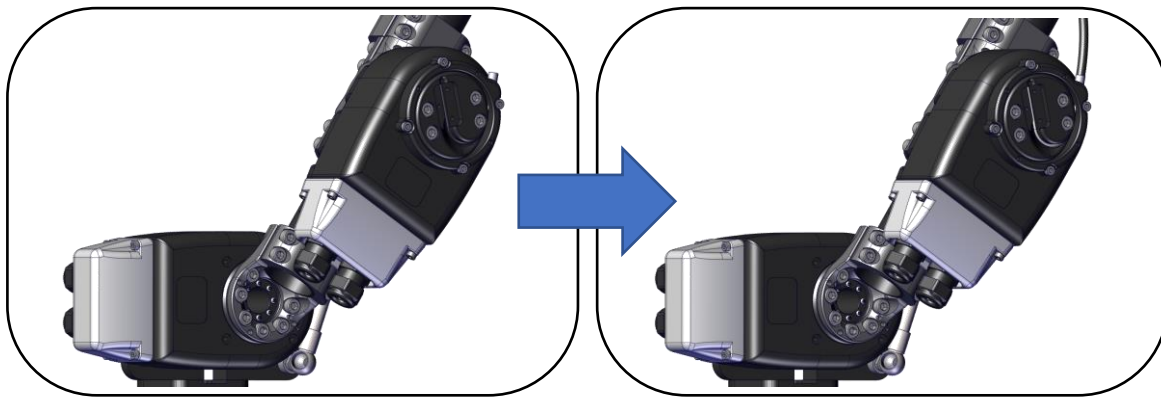
Cable Housing
minimum bend radius
25mm

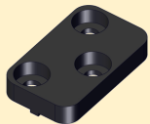
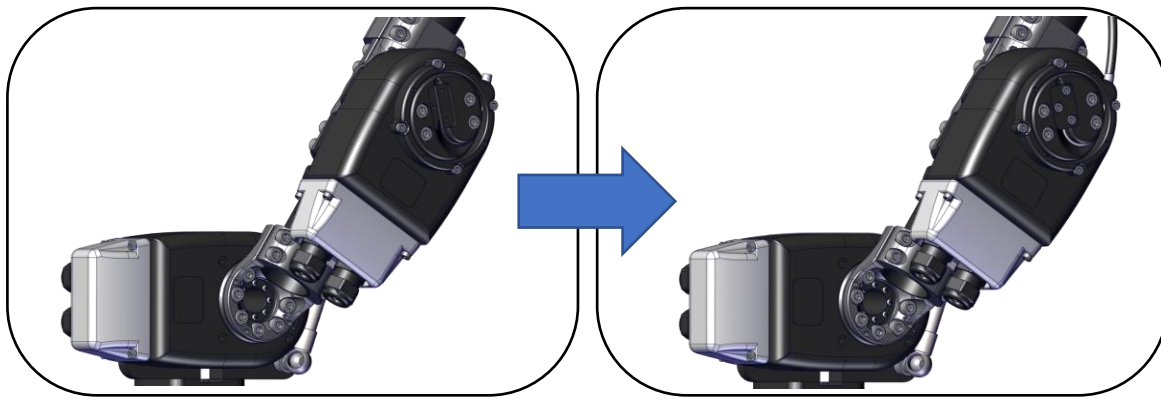




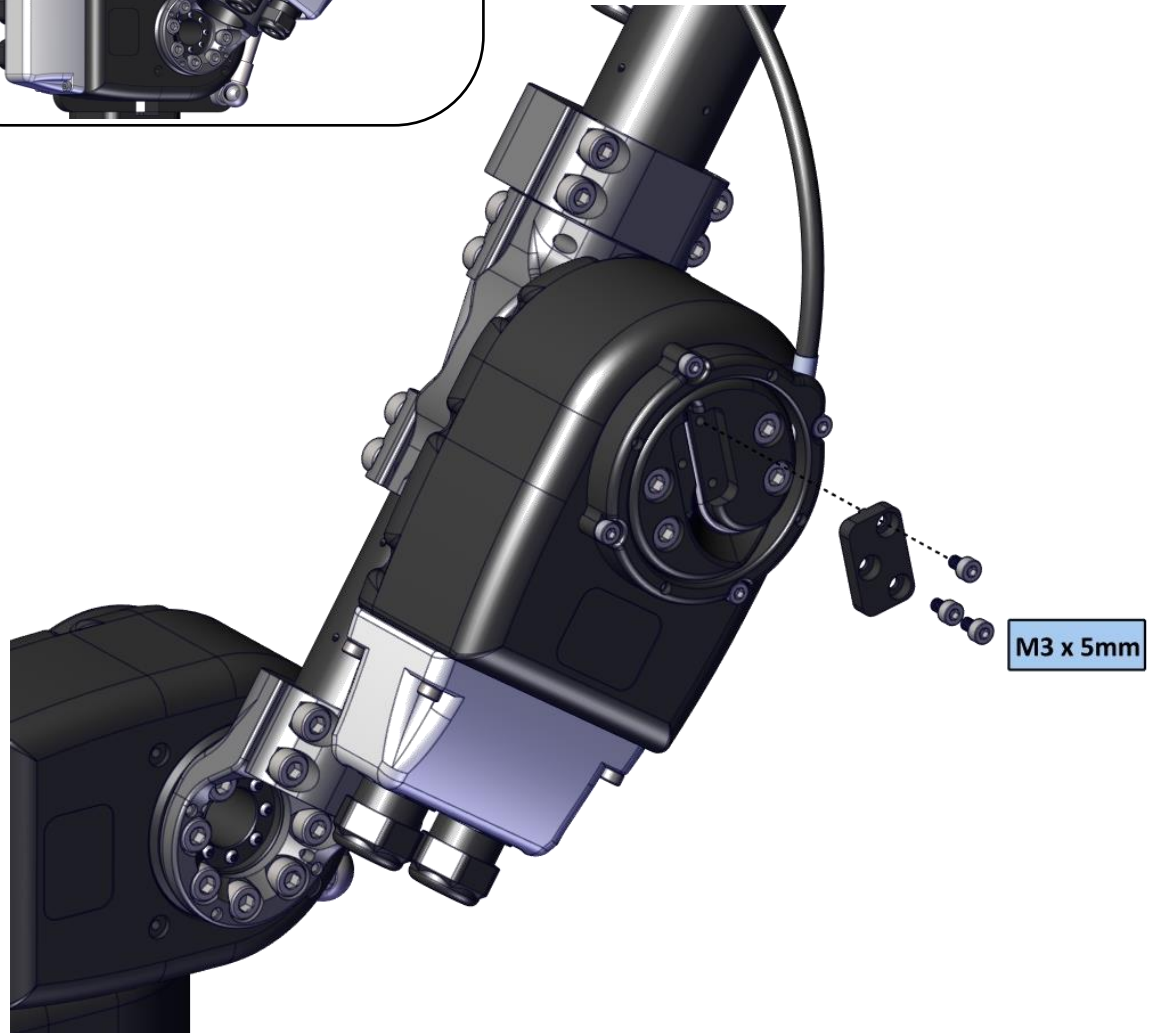
Cable Routing Example (6-Dof Arm)





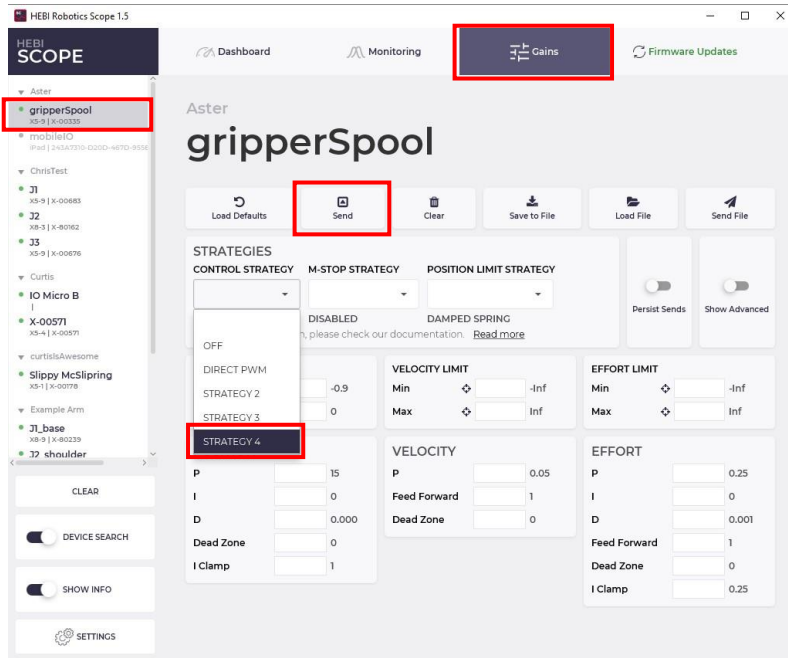


1 x
PM-2292-01
Spool

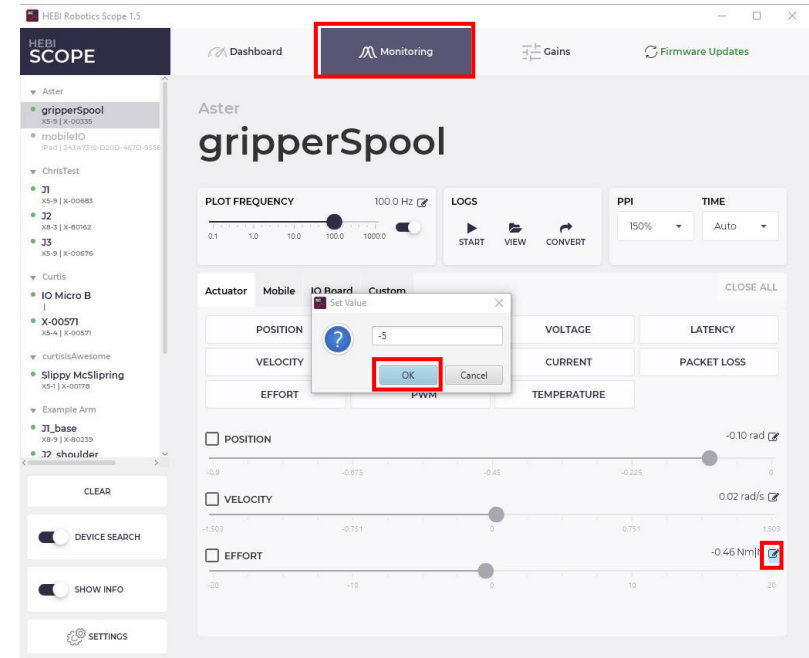


Initializing the Spool, pt. 1

- I. Connect the Spool Module into the network, and turn it on
- II. Open HEBI Scope GUI



- III. Set the Strategy of the Spool Module to “STRATEGY_4”
 1. Click on your Spool Module
 2. Go to “Gains” tab
 3. Use the Control Strategy drop down menu to select a Suitable Strategy for your Application
 4. Click “Send”

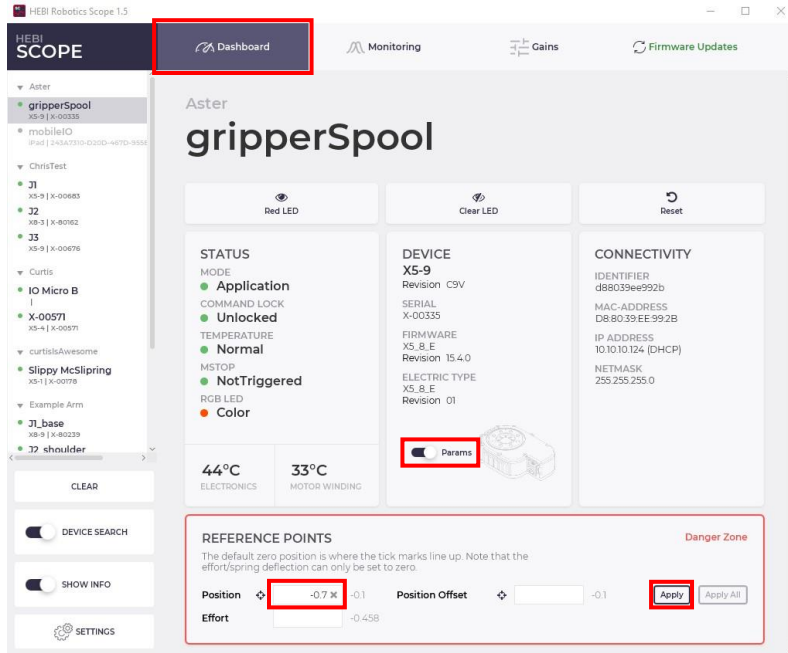


- IV. Command the Effort to -5 Nm
 1. Go to “Monitoring” tab
 2. Click the “Target Button” for the Effort
 3. Type “-5” and Click “OK”



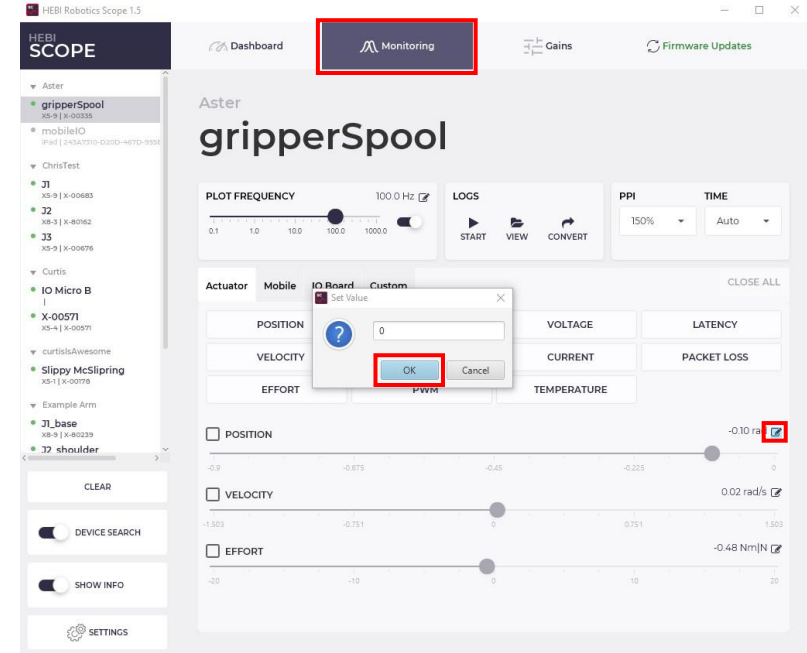
The Spool will wind the Cable and close the Fingers.

Initializing the Spool , pt. 2



V. While Commanding the Effort, set the current position to “-0.7”

1. Go to “Dashboard” tab
2. Toggle “Params” as shown
3. Type “-0.7” for Position
4. Click “Apply”



VI. Stop commanding the effort, and command the position to 0.

1. Go to “Monitoring” tab
2. Click the “Target Button” for Position
3. Type “0” and Click “OK”

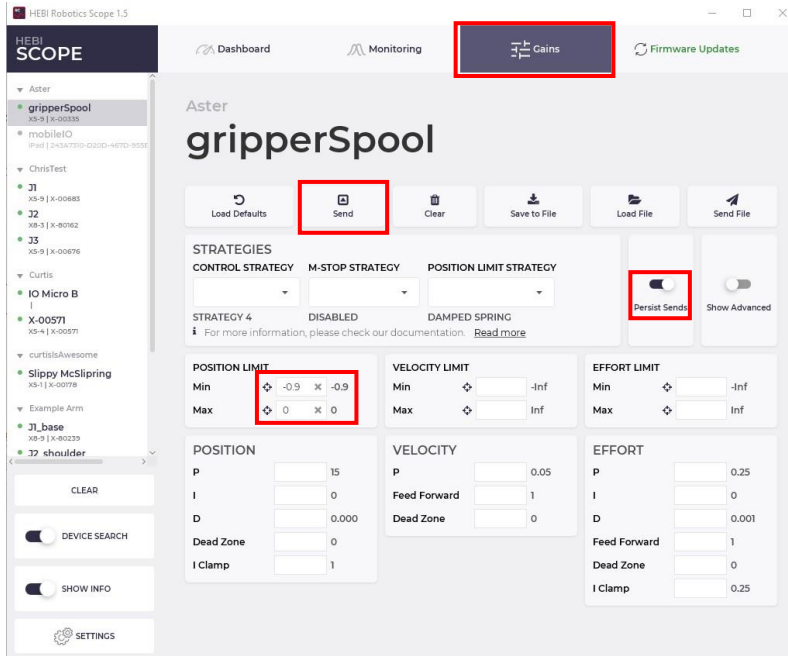


The Spool will unwind the Cable and open the Fingers.

To close the gripper, turn the spool clockwise.

To open the gripper, command the spool to zero position.

Initializing the Spool, , pt. 3



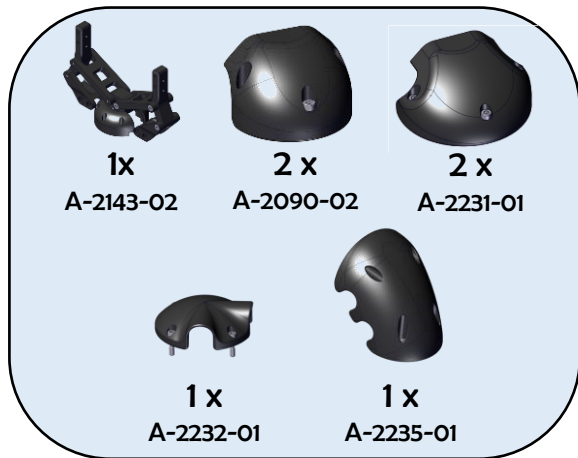
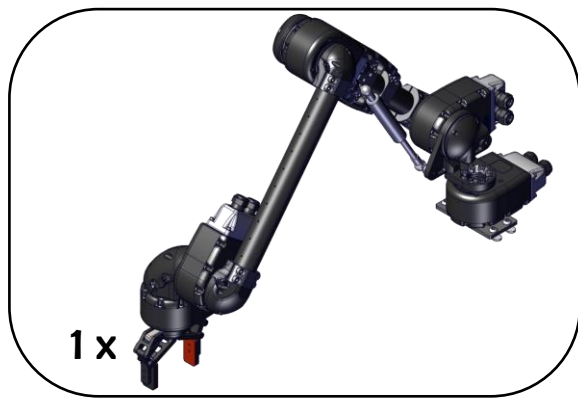
If the Safety Limits are not set, the spool can turn to a position greater than zero, and break the cable.

To close the gripper, turn the spool clockwise (negative effort).

To open the gripper, turn the spool counter-clockwise (positive effort)

VII. Set Safety Limits for the Spool

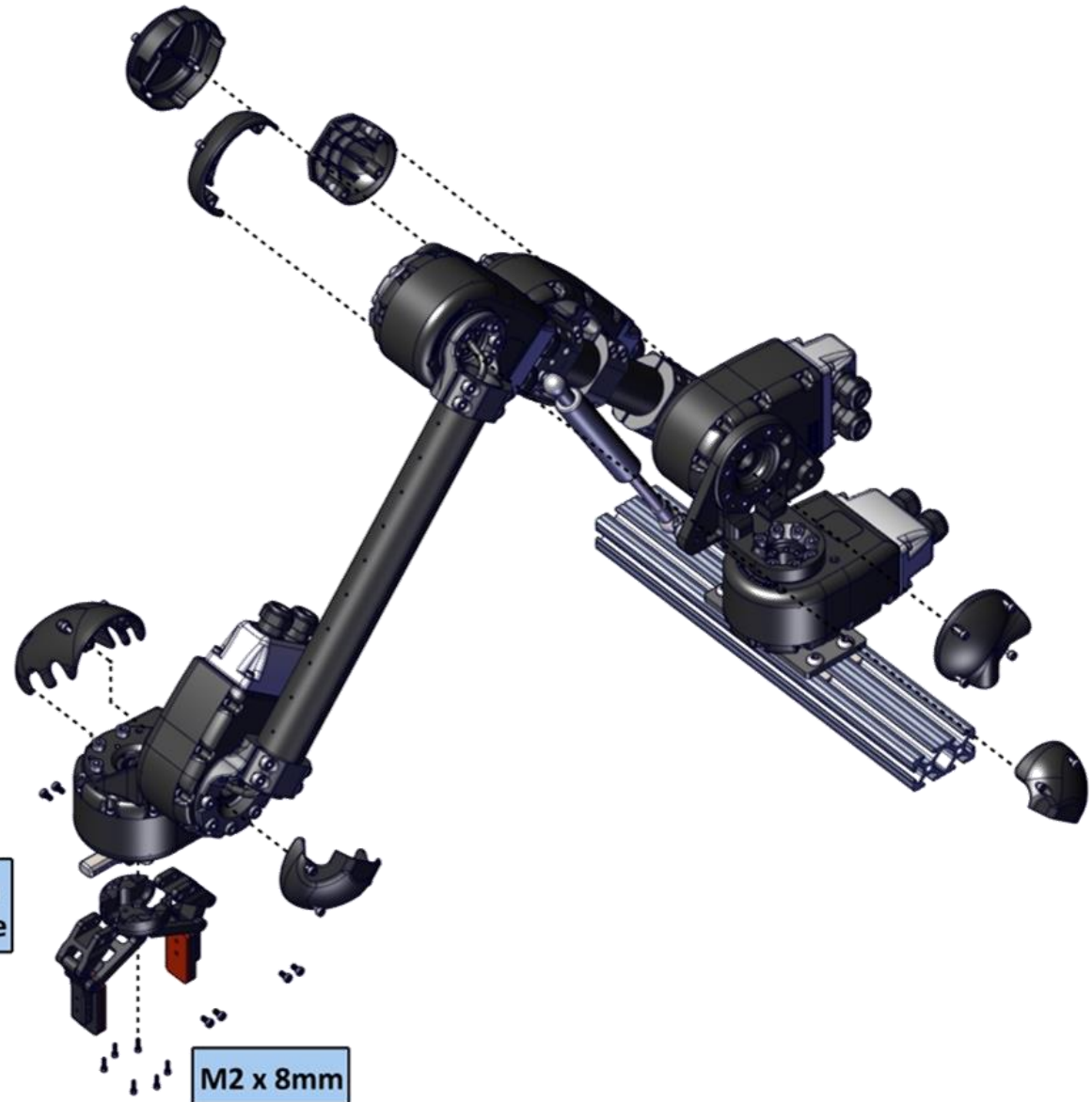
1. Go to "Gains" tab
2. Type "-0.9" for Min Position
3. Type "0" for Max Position
4. Toggle "Persist Sends" as shown
5. Click "Send"



Install cables before
adding caps

M3 x 6mm
Low Profile

M2 x 8mm



Additional Accessories

- Power Supply, 36V 220W (A-2098-36)
 - Comes with correct Molex Minifit Jr 2 connector
- HEBI I/O Board (A-2116-01)
 - Integrate with 3rd party end effectors or tools using HEBI APIs
- HEBI Gripper
 - Cable driven gripper keeps weight away from end of arm
 - *Modules sold separately*



