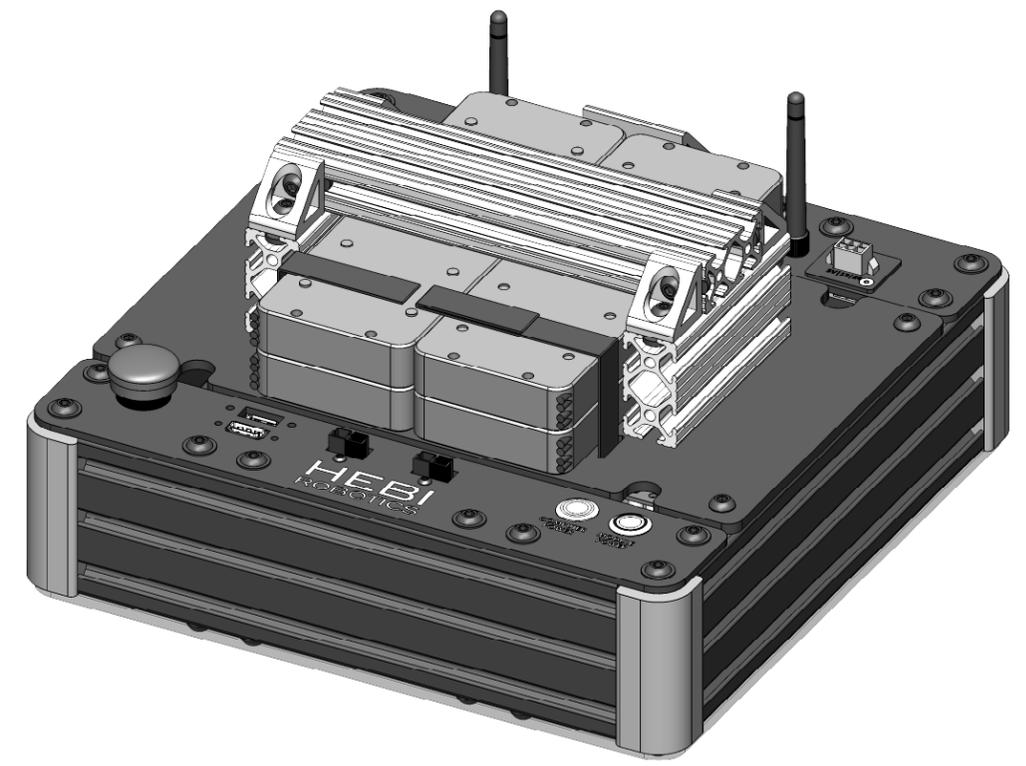
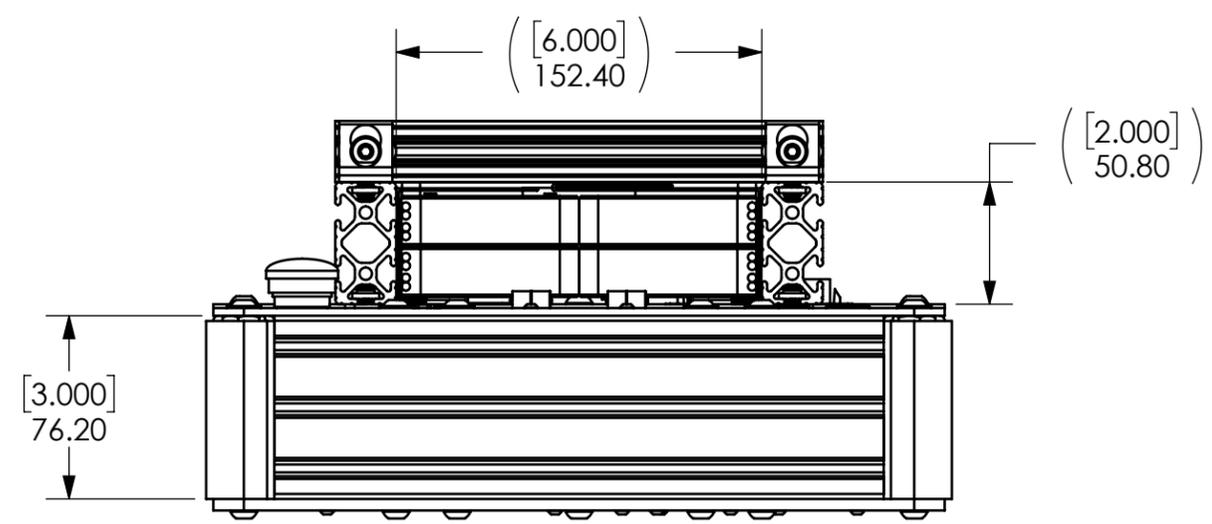
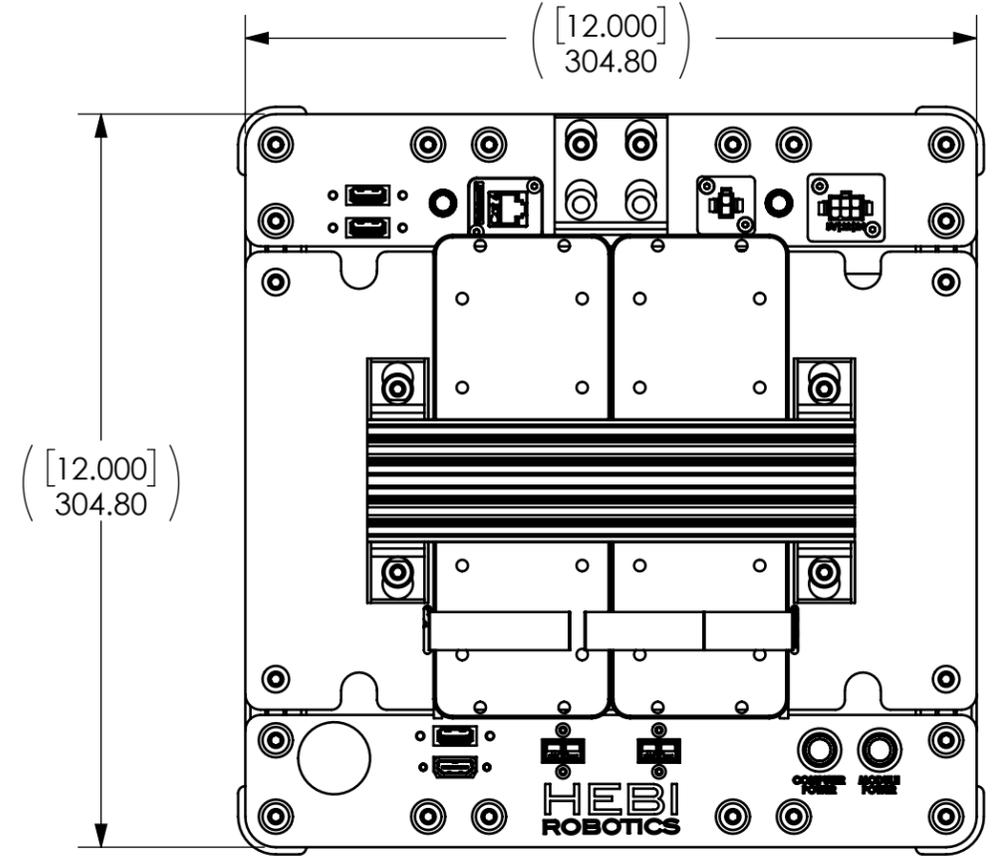


6 5 4 3 2 1

REVISIONS			
REV.	DESCRIPTION	DATE	APPROVED
A.01	INITIAL DRAFTING AND LAYOUT.	19 JAN 2018	A WILLIG
A.02	UPDATED TO 3" TALL ALUMINUM EXTRUSION.	10 SEPT 2018	A WILLIG
A.03	ADDED ACCESS POINT ANTENNAS TO MODEL	12 SEPT 2018	A WILLIG
A.04	UPDATED BULKHEAD CONNECTIONS	18 SEPT 2018	A WILLIG
A.05	ADDED M-STOP BUTTON	7 DEC 2018	A WILLIG
A.06	UPDATED 1/4-20, 3/8" LENGTH BOLTS TO FLANGED BOLTS	14 JAN 2019	A WILLIG



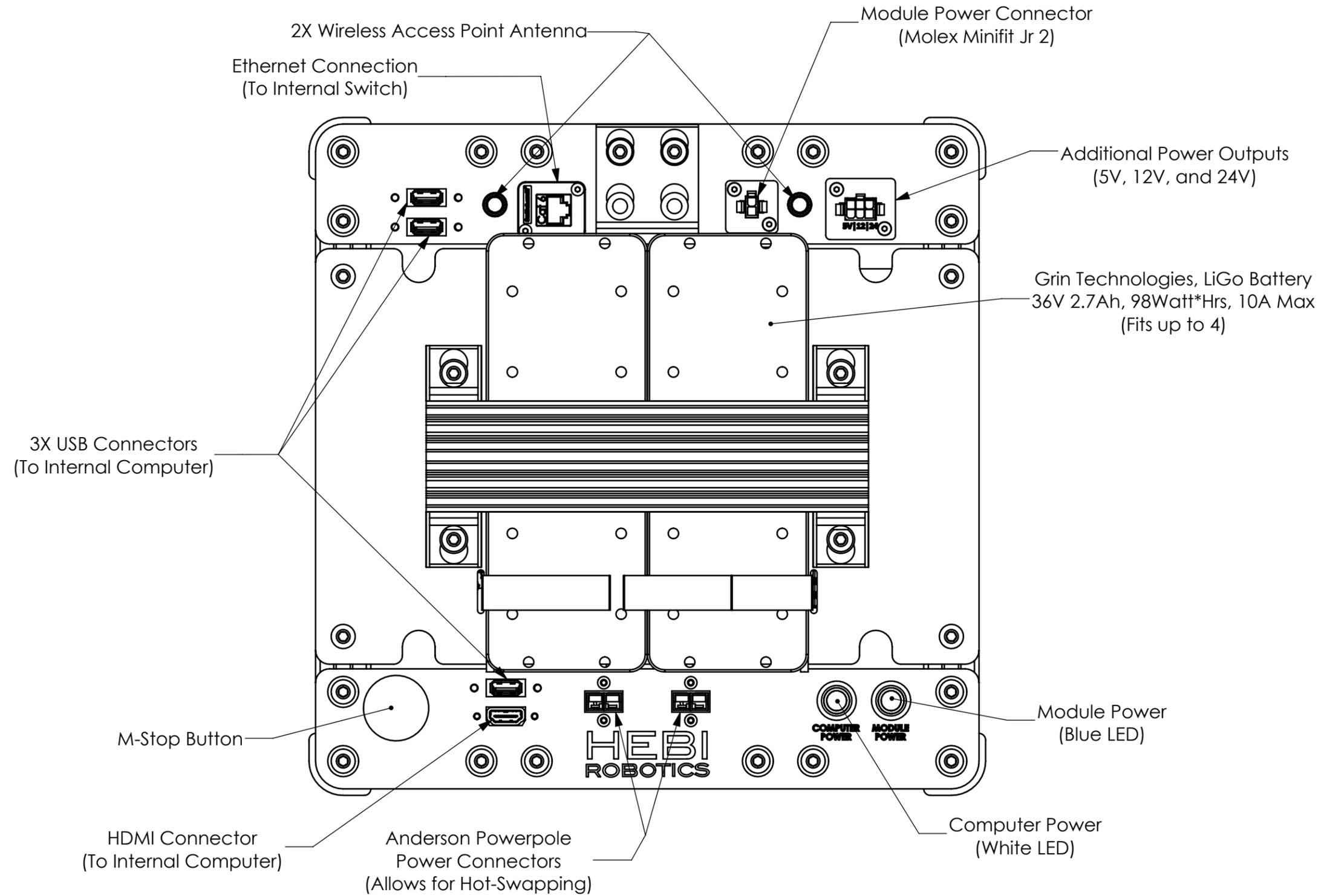
THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF HEBI ROBOTICS, INC. ANY REPRODUCTION IN PART OR WHOLE WITHOUT WRITTEN PERMISSION OF IS PROHIBITED.

AUTHORIZATION		<b>HEBI ROBOTICS, INC.</b>	
DFTG: A WILLIG	12 JAN 2018	91 43rd St, Suite 200 Pittsburgh, PA 15201	
DSGMR: A WILLIG	JAN 2018	PROJECT: HEBI Kits	
CHKR:		Modular Chassis Kit, Square	
ENGR:			
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN MM DO NOT SCALE DRAWING		SIZE <b>B</b>	REV <b>A.06</b>
TOLERANCES: X.X ±.30 X.XX ±.08 ANGLES ±1.00°		SCALE: 1:3	WEIGHT: 14784.604 G
		SHEET 1 OF 2	

FILE NAME: Square Chassis Layout.SLDDRW

6 5 4 3 2 1

# BULKHEAD LAYOUT



THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF HEBI ROBOTICS, INC. ANY REPRODUCTION IN PART OR WHOLE WITHOUT WRITTEN PERMISSION IS PROHIBITED.

**HEBI ROBOTICS, INC.**  
 91 43rd Street, Suite 200  
 Pittsburgh, PA 15201

SIZE <b>B</b>	<b>Square Chassis Layout</b>	REV <b>A.06</b>	VER
SCALE: <b>1:5</b>		SHEET <b>2</b>	OF <b>2</b>