



# R-Series Gripper

Wire Actuated 2-Finger Gripper Assembly Instructions



#### **General Warnings and Cautions**

#### Danger (May cause serious injury or death)

- Keep water, flammables, solvents and other liquids clear from **unsealed** actuator.
- Keep fingers away from moving parts during operation.
- Cut power immediately if actuator emits strange odors or smoke.
- Keep actuator out of reach of children.

#### Warning (May cause injury or damage to actuator)

- Do not expose the actuator to permanent and strong magnetic fields.
- Do not force screws into the bottom of the actuator. R8 = 8mm Tap Depth
- Use provided hardware with accessories and hand tighten as needed.
- Attempts to disassemble actuator will void the warranty and may cause permanent damage.

#### \*Sealing (R-Series Actuators are IP67 when properly used)\*

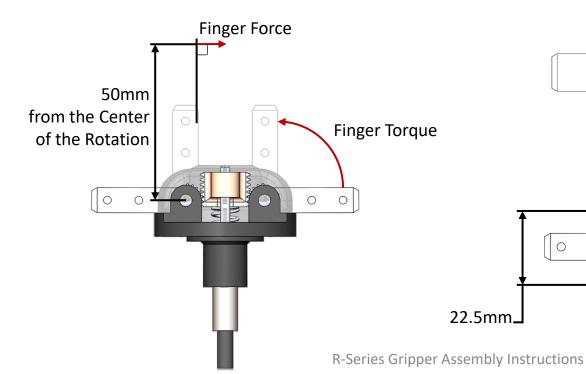
Please refer to all online documentation for proper sealing techniques of the actuator.

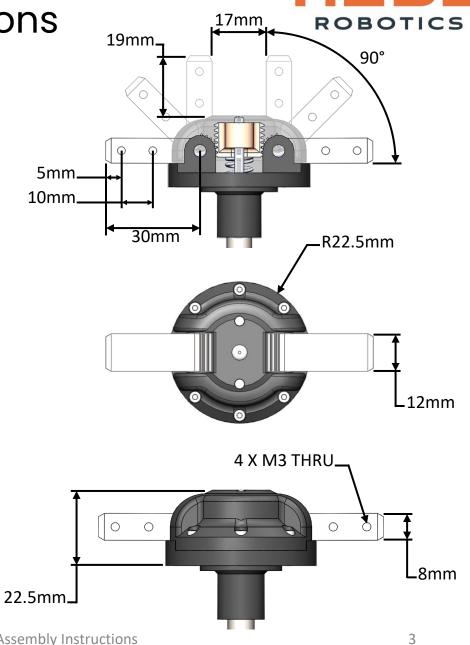
For more information please visit: docs.hebi.us

Technical Specifications

<u>Spool</u> <u>Module</u>	<u>Max Finger</u> <u>Torque</u>	<u>Max Finger</u> <u>Force at 50mm</u>
R8-3	0.4 Nm	8 N
R8-9**	1.1 Nm	23 N
R8-16	2.0 Nm	40 N

<sup>\*</sup> Values assume a symmetric two-finger grasp

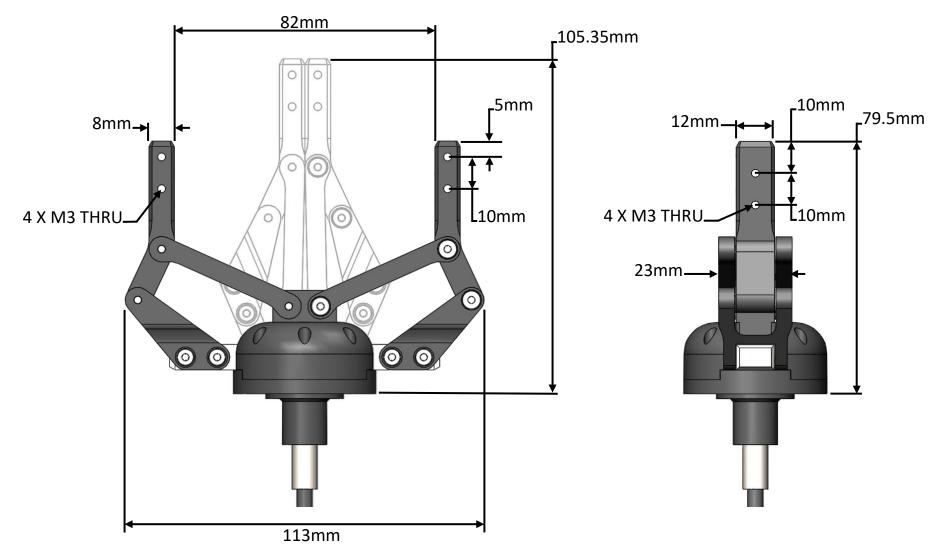




<sup>\*\*</sup> Default Module

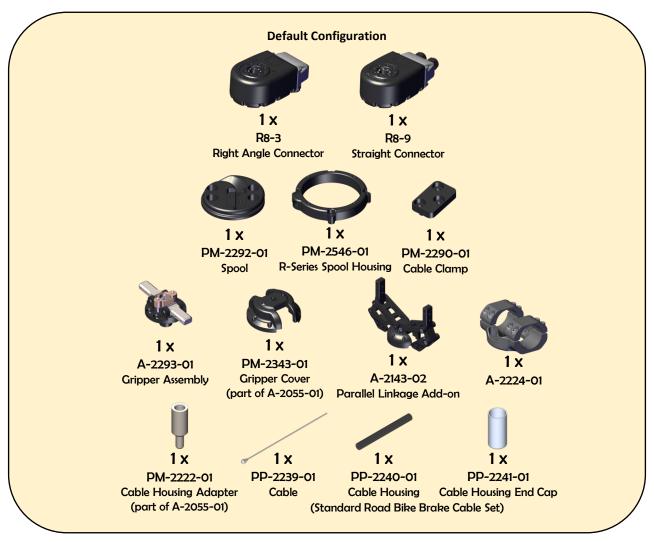




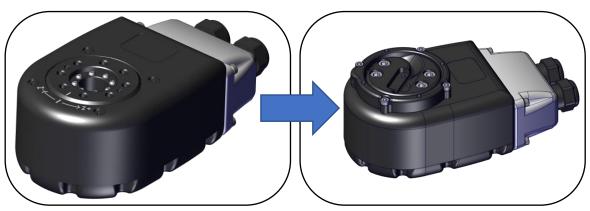


#### **Bill of Materials**



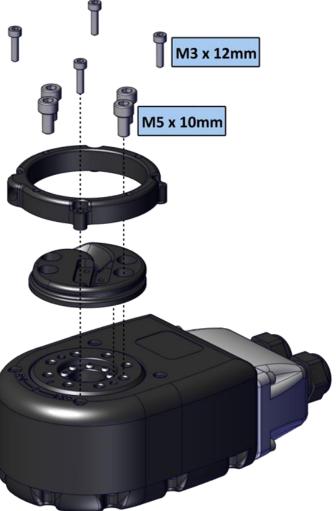


<sup>\*</sup>R-Series Actuators sold separately\*
\*Fasteners included, not shown\*







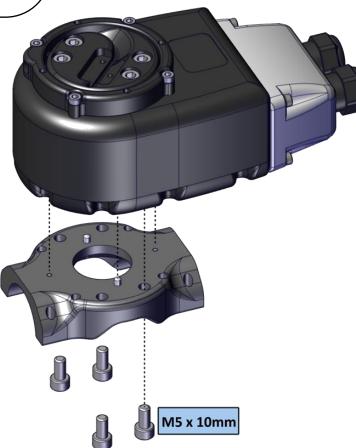


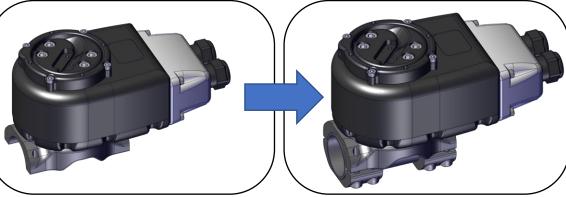






PM-2519-01 Housing Mid-Tube Mount

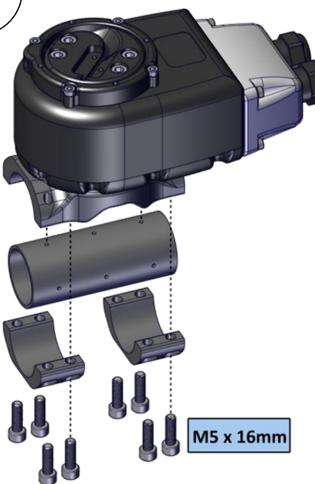


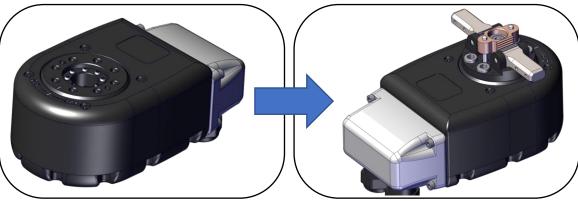






2 x PM-2148-02 Tube Clamp





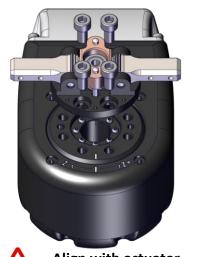




1 x A-2293-01 Gripper Assembly



1 X R8-3 Right Angle Connector



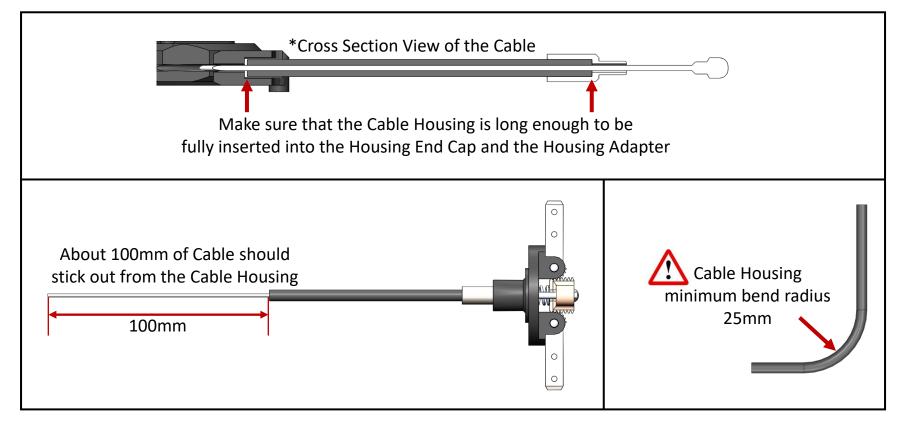
Align with actuator output hub tick mark (Fingers perpendicular to the tick mark)





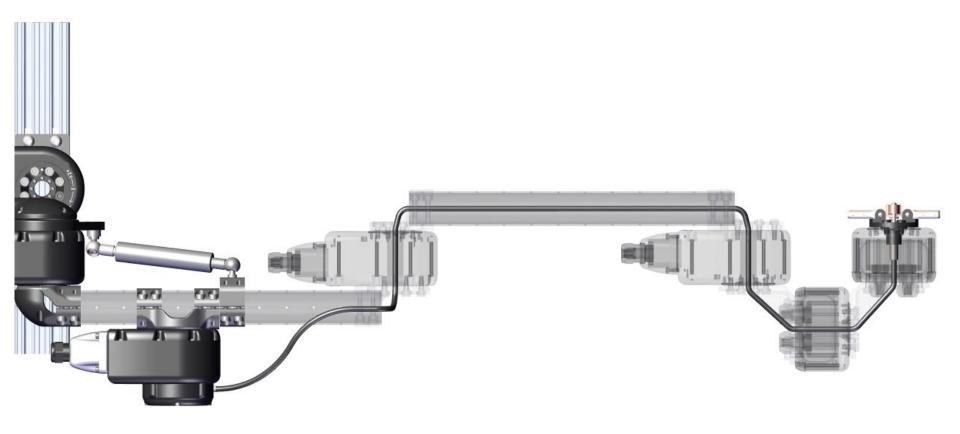
### Running the Cable Through

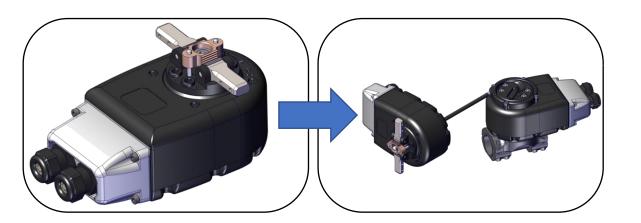
- Make sure to use a Standard Road Bike Brake Cable.
- Run the cable to fit your system.
- Run both the cable and the cable housing before cutting them to ensure that the cable is long enough.
- Cut the cable housing first, and then cut the cable.



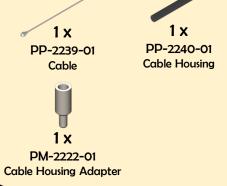


## Cable Routing Example (6-Dof Arm)

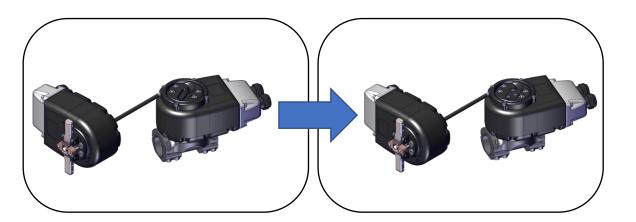
















PM-2290-01 Cable Clamp

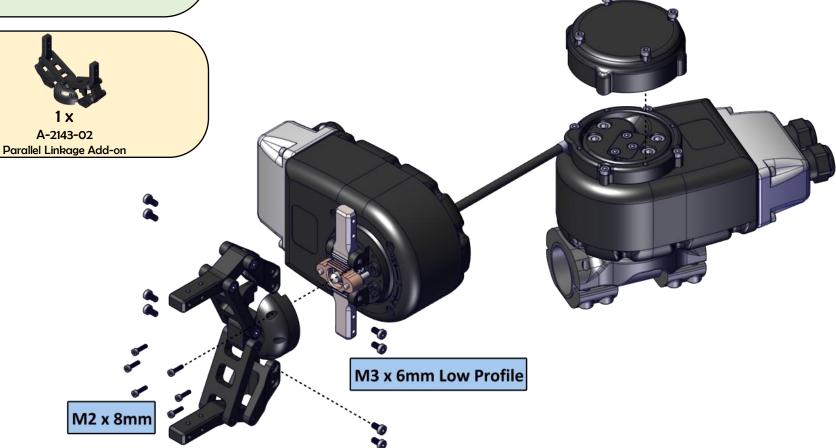


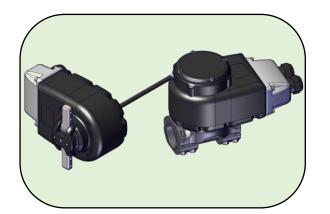
Do NOT operate the gripper at this state. The pins at the pivot of the fingers will fall out.



1 x A-2143-02











Use PM-2343-01 when the parallel linkage is not needed.



1 X PM-2343-01 Gripper Cover

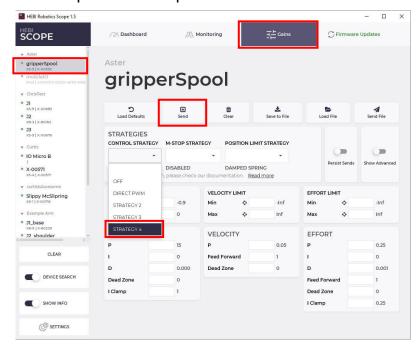
M2 x 8mm



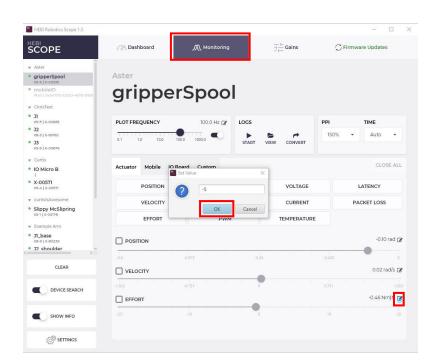


### Initializing the Spool, pt. 1

- Connect the Spool Module into the network, and turn it on
- Open HEBI Scope GUI



- Set the Strategy of the Spool Module to "STRATEGY 4"
  - Click on your Spool Module
  - Go to "Gains" tab
  - 3. Use the Control Strategy drop down menu to select a
  - Suitable Strategy for your Application



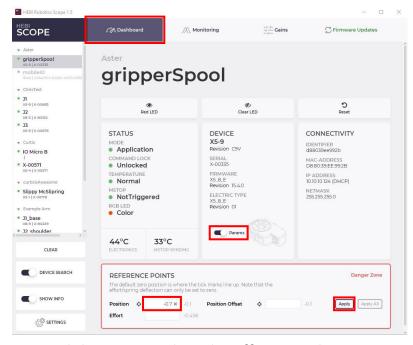
- Command the Effort to -5 Nm
  - Go to "Monitoring" tab
  - Click the "Target Button" for the Effort
  - 3. Type "-5" and Click "OK"

The Spool will wind the Cable and close the Fingers.

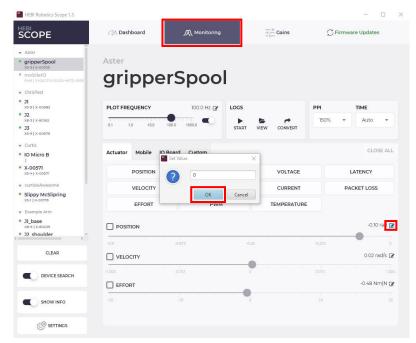
Click "Send"



### Initializing the Spool, pt. 2



- V. While Commanding the Effort, set the current position to "-0.7"
  - 1. Go to "Dashboard" tab
  - 2. Toggle "Params" as shown
  - 3. Type "-0.7" for Position
  - 4. Click "Apply"



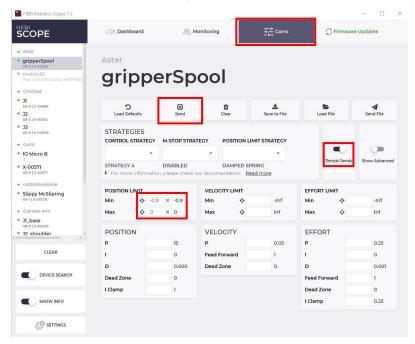
- VI. Stop commanding the effort, and command the position to 0.
  - 1. Go to "Monitoring" tab
  - 2. Click the "Target Button" for Position
- 3. Type "0" and Click "OK"

The Spool will unwind the Cable and open the Fingers.

- \*To close the gripper, turn the spool clockwise.\*
- \*To open the gripper, command the spool to zero position.\*



### Initializing the Spool, pt. 3



#### VII. Set Safety Limits for the Spool

- 1. Go to "Gains" tab
- 2. Type "-0.9" for Min Position
- 3. Type "0" for Max Position
- 4. Toggle "Persist Sends" as shown
- 5. Click "Send"



- \*If the Safety Limits are not set, the spool can turn to a position greater than zero, and break the cable.\*
- \*To close the gripper, turn the spool clockwise (negative effort).\*
- \*To open the gripper, turn the spool counterclockwise (positive effort)\*

