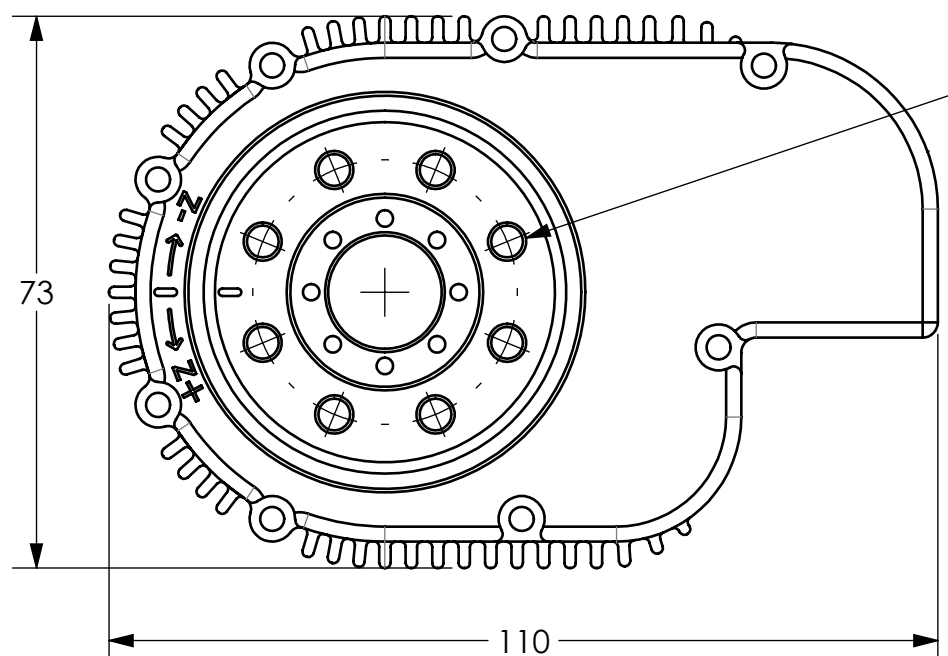
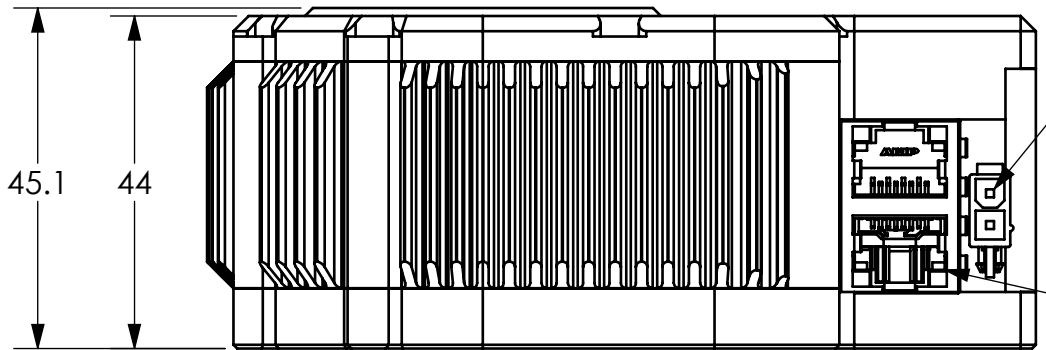


REVISIONS			
REV.	DESCRIPTION	DATE	APPROVED
A.01	INITIAL DRAFTING AND LAYOUT.	15 JUN 2016	D ROLLINSON
A.02	UPDATED DIMS AND TITLE BLOCK	3 MAY 2017	A WILLIG

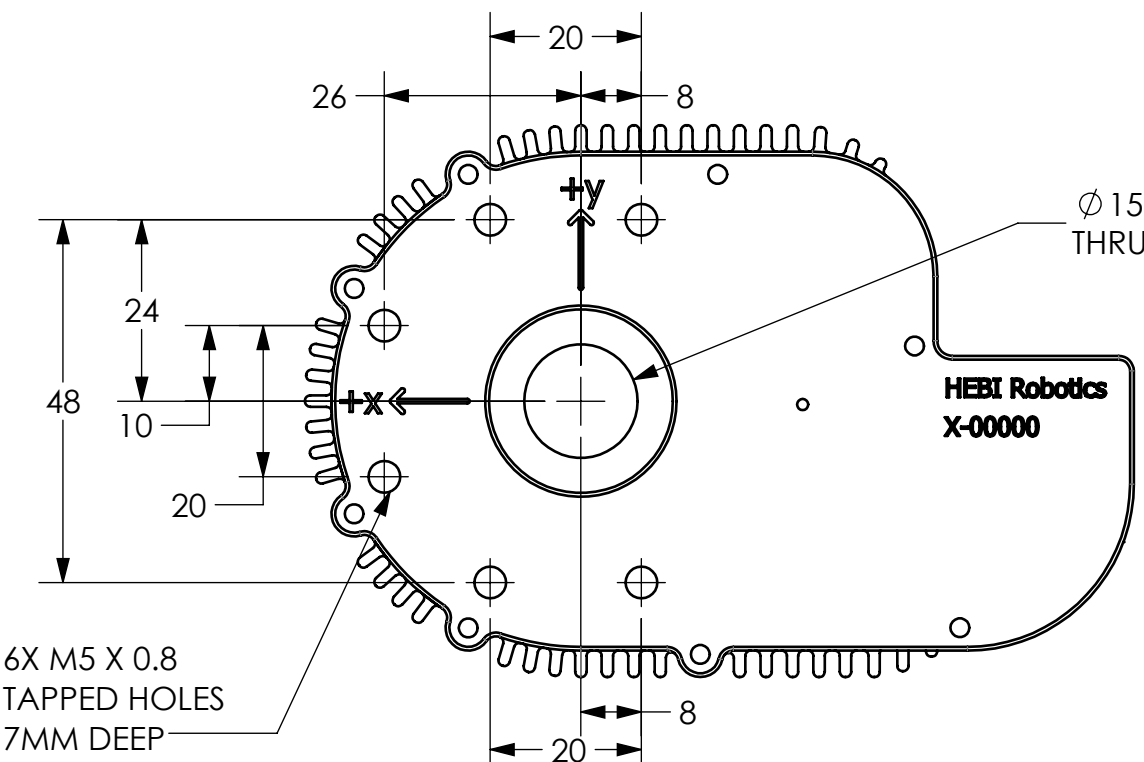
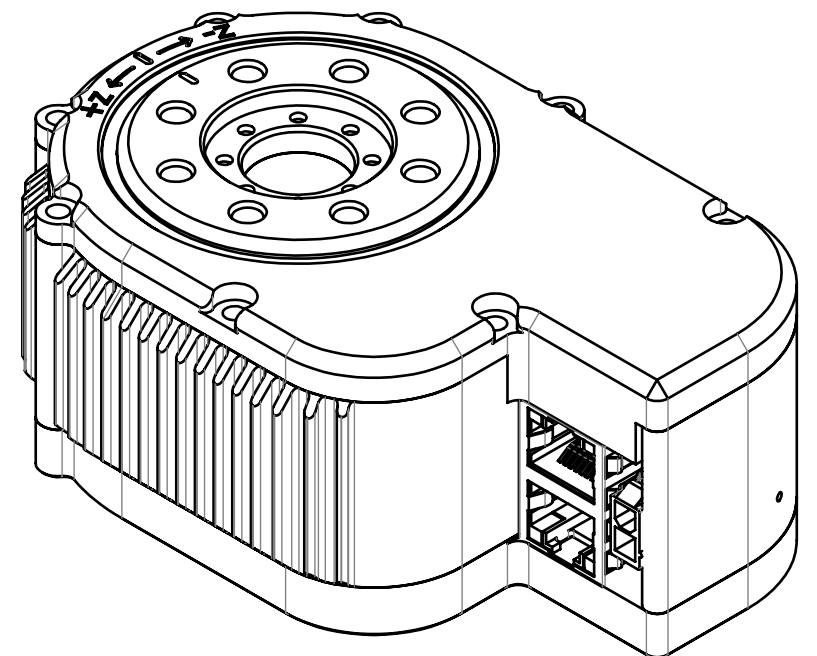


8X M5 X 0.8
TAPPED HOLES
7MM DEEP



POWER CONNECTION
MOLEX MINI-FIT JR
24-48 VDC RECOMMENDED

DATA CONNECTION
2X RJ45
10/100 ETHERNET



Ø15
THRU BORE FOR WIRING

6X M5 X 0.8
TAPPED HOLES
7MM DEEP

HEBI Robotics
X-00000

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UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN MM DO NOT SCALE DRAWING TOLERANCES: X.X ±.40 X.XX ±.08 ANGLES ±0.50° SURFACE TEXTURE 64 REMOVE ALL BURRS AND BREAK ALL SHARP EDGES TO 0.3 MM MAX CAD GENERATED DRAWING, DO NOT MANUALLY UPDATE INTERNAL MODEL REV: A.01	AUTHORIZATION		HEBI ROBOTICS, INC.	
	DFTG:		5001 Baum Blvd, Suite 780 Pittsburgh, PA 15213	
	DSGMR:		PROJECT: X-Series Actuator	
	CHKR:		X8 Actuator Dimensions	
	ENGR:		MATERIAL:	
		TREATMENT:		SIZE B X8-Dimensions
		SCALE: 1:1	WEIGHT:	REV A.02
				VER 1 OF 1